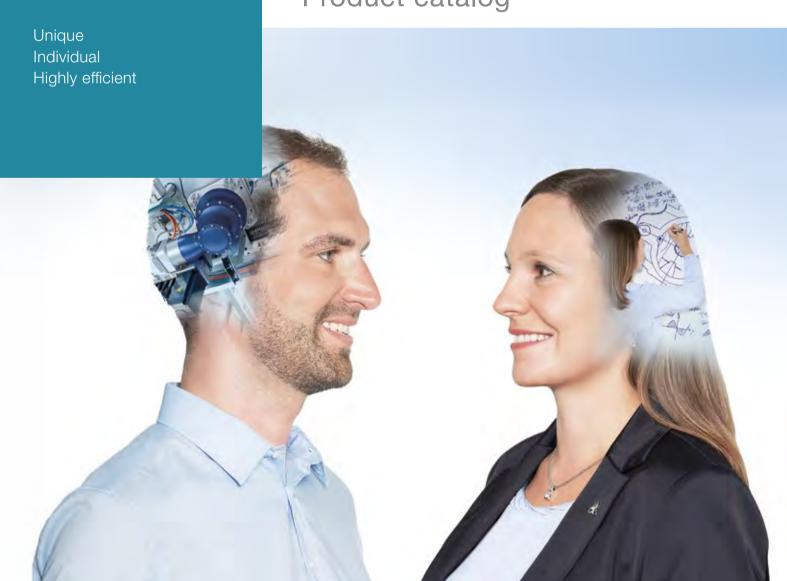




alpha Premium Line Product catalog





alpha Premium Line Product catalog

Unique Individual Highly efficient

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All technical specifications were correct at the time of going to print. We are continually developing our products and therefore reserve the right to make modifications. This documentation is subject to occasional errors. Please appreciate that legal claims cannot be asserted as a result of incorrect specifications, illustrations or descriptions. The text, photos, technical drawings and any other illustrations printed in this publication are protected property of WITTENSTEIN alpha GmbH.

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PERFORMANCE

Performance where it counts:

High torque, outstanding precision and high power density – essential for our products and systems.

FUTURE PROOF

We live processes:

Only those who know the exact details of customer processes and requirements are in a position to develop solutions that offer added value in the short and long term.

SCALABILITY

You never make compromises:

Whatever the performance area – we offer solutions that grow with your requirements.



WITTENSTEIN

alpha

It is good to know today what will be needed tomorrow. Applying it in practice is even better. We develop technology that shapes the future – ENGINEERING FUTURE SOLUTIONS.

EFFICIENCY

We like it "lean":

We offer products and systems that are energy-efficient and require minimal installation space in machines.

AVAILABILITY

You need reliability:

We have the widest range of products on the market and can implement your application "just in time".

CONNECTIVITY

We think in terms of interfaces:

All of our systems can be integrated in a wide range of peripherals.



INIRA®







alpha Linear Systems

alpha Basic Line

cynapse

2019

2016

SIZING ASSISTANT V-Drive Family

2017



premo®

2018

CAD POINT













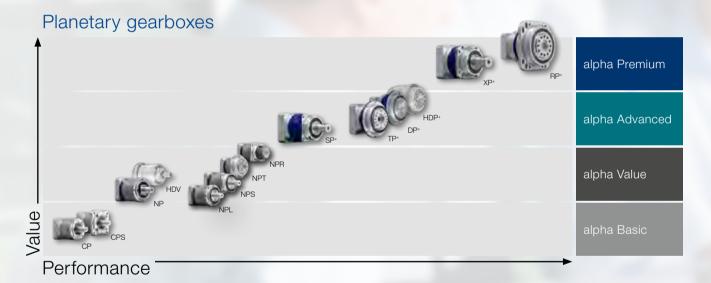
WITTENSTEIN

WITTENSTEIN alpha on all axes

Complete drive solutions under one roof

We offer the best solutions for almost every application. In addition to gearboxes, our product portfolio includes a wide range of drive solutions with linear systems and servo actuators. Adapted accessories such as couplings and shrink disks round off the product portfolio.

The diagrams below provide a quick overview of our product portfolio for a wide variety of requirements and applications:

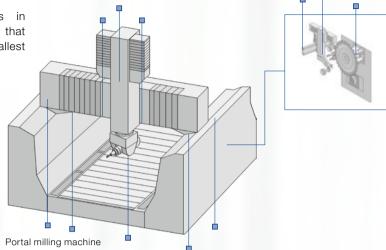




Know-how in every sector

Our solutions range from high-precision axes in manufacturing systems to packaging machines that must operate with maximum productivity in the smallest installation space. Overview:

- · Machine tools and production technology
- · Food and packaging machines
- · Wood working machinery
- · Printing and paper machines
- · Robotics and automation



Linear systems Premium Linear System - RP Premium Linear System - RP Premium Linear System - RP Advanced Linear System - TP alpha Advanced Advanced Linear System - SP alpha Advanced alpha Value alpha Value alpha Basic



Performance

WITTENSTEIN alpha Tools – several ways to reach your objectives

Our software portfolio helps you choose the right drive

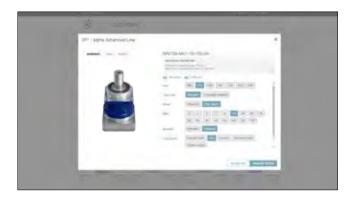
You can conveniently download dimension sheets and CAD data, select the best gearbox quickly and easily design complex kinematic sequences in detail – our software solutions offer various methods of selecting the best, most reliable drive on all axes.



CAD POINT

- Your Smart Catalog
- Performance data, dimension sheets and CAD data for all types of gearbox
- · Comprehensive documentation of the selection
- · Available online without logging in

www.wittenstein-cad-point.com

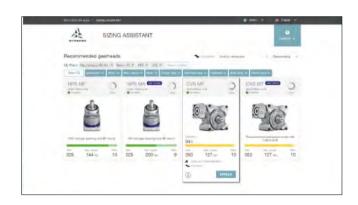




SIZING ASSISTANT

- Your Gearbox within Seconds
- · Efficient gearbox selection in seconds
- · Access by specifying application or motor
- $\cdot\,$ Information about price and delivery time
- · Possibility of requesting quotation directly
- · Available online without logging in

www.sizing-assistant.com





cymex®5

- Calculate on the Best
- · Detailed calculation of complete drive trains
- · Precise simulation of motion and load variables
- · Downloadable software for complex designs

www.wittenstein-cymex.com



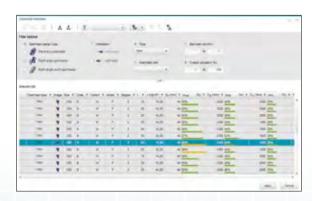


cymex®5 is the current standard

With cymex® 5, the dimensioning and design of complete drive trains (application + transformation + gearbox + motor) is now fast, simple and reliable. Calculation is made much easier through predefined standard applications. Consideration for all major influencing factors guarantees an optimal design and increases the efficiency of your machine.

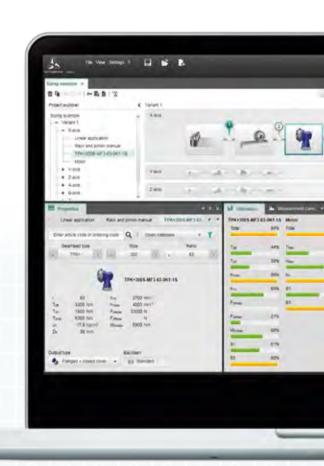
cymex® 5 can define any number of axes simultaneously

In contrast to other design tools, cymex® 5 can define any number of axes at the same time. The version calculation is up to 60% quicker as a result.



cymex® 5 has an extremely extensive database

More than 14,000 motors from the 50 most prominent motor manufacturers are stored in the design tool. Continuously updated, always state-of-the-art. Moreover, more than 8,000 gearbox versions from WITTENSTEIN alpha and over 200 combinations of linear systems with all relevant technical specifications can be found here.

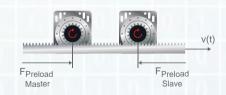


Free download

The basic version of cymex® 5 design software is available as a free download.



www.wittenstein-cymex.com



cymex® 5 incorporates the completely new Master/Slave function*

The Master / Slave function enables the electrically clamped configuration of two drives. The mutual tensioning of master and slave eliminates the backlash in the drive train and provides for a high degree of rigidity in the machine.

cymex[®]5



cymex® 5 has a unique optimization calculator*

During the design process, cymex® 5 provides optimization suggestions for the selected gearbox, which increase reliability and efficiency while ensuring your gearbox has the perfect dimensions e.g. through downsizing. This saves on costs and reduces the installation space in the machine.





cymex® 5 offers comprehensive documentation

Following the geometry comparison, cymex® 5 creates calculation documentation and generates data sheets for gearbox and motor on request. Furthermore, the 2D and 3D CAD data of selected components can be retrieved.











cymex® 5 enables the precise simulation of motion and load variables

The optimized software offers many options for the individual design of the drive train. These have been integrated to supplement the existing applications already in cymex® 3: the crank, conveyor, center winder and feed roll.

alpha Premium Line – unique, individual solutions that offer unparalleled power density

The requirements for highly complex applications used in machine tools or laser technology, for example, are becoming increasingly demanding and standard products are often unable to meet them. The alpha Premium Line is a completely new product program developed to meet the most demanding requirements. In addition to the products, we primarily focus on offering comprehensive consultancy services to ensure that your requirements are taken into full consideration and maximum machine utilization is achieved. We aim to provide unique "Best in Class" solutions that significantly exceed current standards and help you design your plants more efficiently.

Maximum power density

We increased the performance of our gearboxes by up to 200 % compared to other commercially available standard gearboxes. Our Premium products therefore make a direct contribution to enhancing the performance of your plant.

Maximum positioning accuracy

On request, the Premium planetary gearboxes are available with torsional backlash of less than one arc minute. In combination with maximum torsional rigidity, this backlash guarantees outstanding positioning accuracy.

Easy installation

Specially designed output configurations allow for quick and easy installation.

Top engineering and expert consultation

We use our extensive engineering expertise to develop unique solutions and produce the perfect design for your drive train. Our highly qualified employees provide support and advice from the initial idea and throughout the entire life cycle of your application.

alpha Premium solutions. Tailored precisely to meet your needs.

More performance in less space

- · if you require an even more compact drive
- · if you wish to enhance the performance of your machine
- · if you require high-performance linear systems





Reaching new heights: the alpha Premium Line

Planetary gearboxes

The unique capabilities of planetary gearboxes from the alpha Premium Line are setting new standards on the market. These compact gearboxes are characterized by a power density far above the current industry standard. Your application can benefit directly from this increase in performance.





Hypoid gearboxes

Maximum power density and high modularity are just two of the special characteristics of our hypoid gearboxes. Furthermore, gearboxes from the alpha Premium Line are characterized by an extremely robust overall design that guarantees a high degree of reliability and a long service life.





remium Line

Bevel gearboxes

The low backlash bevel drives from our alpha Premium Line offer outstanding performance at low ratios during both cyclic and continuous operation. The perfect solution for dynamic applications with demanding requirements with regard to precision, torque and output speed. Increases in the performance of your plant can easily be achieved with a 97 % degree of efficiency.





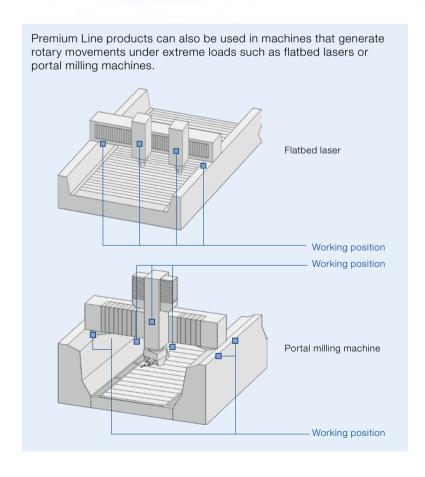


alpha Premium Line in action

RPK⁺ – when high performance is required in a small installation space

Whether laser cutting machines, turning and milling machines, or pipe bending machines – the use of powerful gearboxes with a high degree of positioning accuracy is essential in rack and pinion applications. The compact RPK+ combines these characteristics to achieve high feed forces and accurate positioning in the application.









XP⁺ and RP⁺ planetary gearboxes Unique in performance

XP+ - Perfection in a new dimension

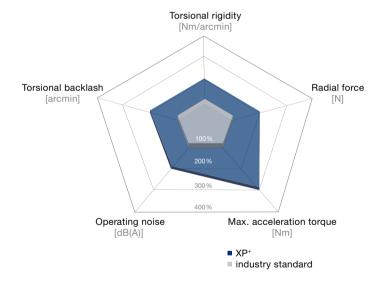


The XP+ with specially designed output and extremely compact design offers new dimensions in power transmission that far exceed industry standards. The optimized interfaces on the output can generate much higher torques that directly benefit your application.

The XP+ impresses with maximum power density

- · if you require an even more compact drive
- · if you wish to enhance the performance of your machine
- · if you require high-performance linear systems

The XP+ compared to the industry standard



Product highlights

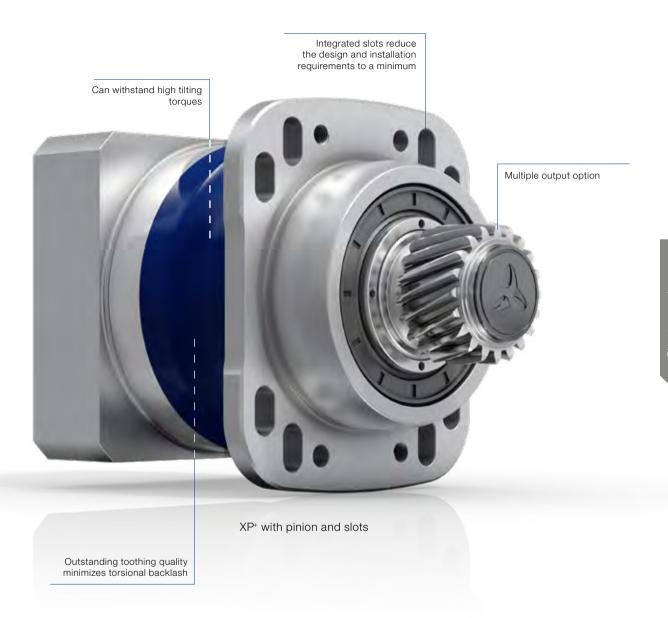
Max. torsional backlash [arcmin] $\leq 1 - 4$ Maximum power density High axial and radial forces



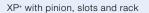
XP+ with splined shaft



XP+ with pinion and slots







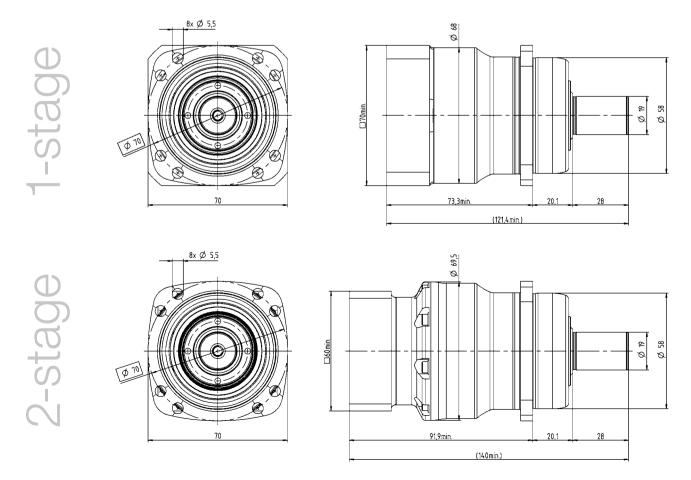


premo® XP Line with pinion

XP* 010 MF 1-/2-stage

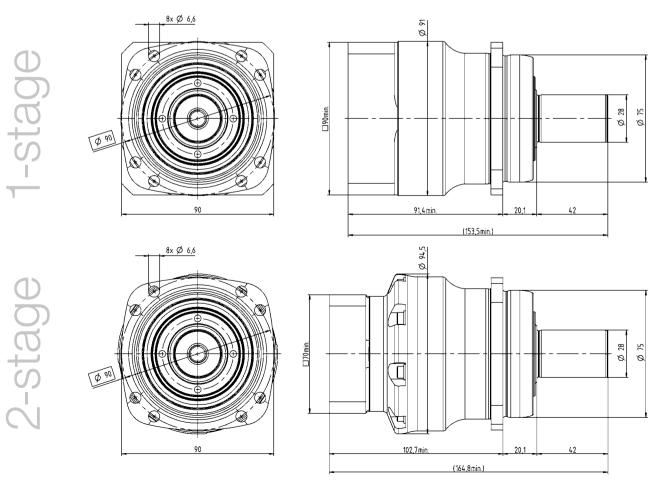
				0 -1
			1-stage	2-stage
Ratio	i		3/4/5/7/8/10	16 / 20 / 25 / 28 / 32 / 35 / 40 / 50 / 64 / 70 / 100
Max. torque a)	_	Nm	56 – 128	50 – 119
Max. torque	1 2a	in.lb	496 – 1133	446 – 1051
Max. acceleration torque	_	Nm	42 – 108	42 – 99
(max. 1000 cycles per hour)	1 2B	in.lb	372 – 956	372 – 876
Nominal torque	7	Nm	21 – 27	34 – 53
(at n _{nN})	1 2N	in.lb	190 – 239	297 – 467
Emergency stop torque	_	Nm	110 – 165	110 – 165
(permitted 1000 times during the service life of the gearbox)	1 2Not	in.lb Nm in.lb Nm in.lb Nm in.lb rpm rpm rpm arcmin Nm/arcmin in.lb/arcmin	974 – 1458	974 – 1458
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) b)	n _{1T}	rpm	3300 – 4000	4400 – 5500
Max. input speed	n _{1Max}	rpm	7500	8500
Max. torsional backlash	j_t	arcmin	Standard ≤ 4 / Reduced ≤ 2	Standard ≤ 5 / Reduced ≤ 3
Torsional rigidity		Nm/arcmin	5 – 6.5	5 – 6.5
Torsional rigidity	C _{t21}	in.lb/arcmin	44 – 58	44 – 58
Max. tilting moment	Λ4	Nm	339	339
iviax. tilting moment	IVI _{2KMax}	$T_{2a} \qquad \frac{Nm}{in.lb}$ $T_{2B} \qquad \frac{Nm}{in.lb}$ $T_{2N} \qquad \frac{Nm}{in.lb}$ $T_{2Not} \qquad \frac{Nm}{in.lb}$ $T_{1n} \qquad rpm$ $T_{1n} \qquad rp$	3000	3000
Operating noise ^{c)}	L _{PA}	dB(A)	≤ 55	≤ 53
Lubrication			Lubricated for life	Lubricated for life
Clamping hub diameter		mm	11 – 19	11 – 14

<sup>a) Application-specific design with cymex® – www.wittenstein-cymex.com
b) For higher ambient temperatures, please reduce input speed
c) At reference ratio and reference speed. Ratio-specific values available in cymex®.</sup>



			1-stage	2-stage
Ratio	i		3/4/5/7/8/10	16 / 20 / 25 / 28 / 32 / 35 / 40 / 50 / 64 / 70 / 100
Max. torque a)	_	Nm	168 – 330	139 – 348
Max. torque -	$T_{2\alpha}$	in.lb	1487 – 2921	1227 – 3080
Max. acceleration torque	Τ	Nm	126 - 275	126 - 303
(max. 1000 cycles per hour)	T_{2B}	in.lb	1115 - 2434	1115 - 2682
Nominal torque		Nm	63 - 81	101 - 145
(at $n_{_{\mathcal{I}\!\!N}}$)	⁷ 2N	$T_{2N} = \begin{array}{c} \hline \\ in.lb \\ \hline \\ T_{2Not} = \begin{array}{c} Nm \\ in.lb \\ \hline \\ in.lb \\ \hline \\ \\ n_{1T} = \begin{array}{c} rpm \\ \hline \end{array}$	558 - 720	101 - 145
Emergency stop torque	Τ	Nm	325 – 390	325 – 418
(permitted 1000 times during the service life of the gearbox)	2Not	T _{2Not} in.lb	2877 – 3452	2877 – 3696
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) ⁽¹⁾	n _{tT}	rpm	2900 – 3100	3500 – 4500
Max. input speed	n _{1Max}	rpm	7500	8500
Max. torsional backlash	j_t	arcmin	Standard ≤ 3 / Reduced ≤ 1	Standard ≤ 4 / Reduced ≤ 2
Torsional rigidity	0	Nm/arcmin	14 – 17	15 – 20
Torsional rigidity	C _{t21}	in.lb/arcmin	124 – 150	133 – 173
Max. tilting moment	14	Nm	675	675
wax. tilting moment	M _{2KMax}	in.lb	5974	5974
Operating noise c)	L_{PA}	dB(A)	≤ 56	≤ 53
Lubrication			Lubricated for life	Lubricated for life
Clamping hub diameter		mm	14 – 24	11 – 19

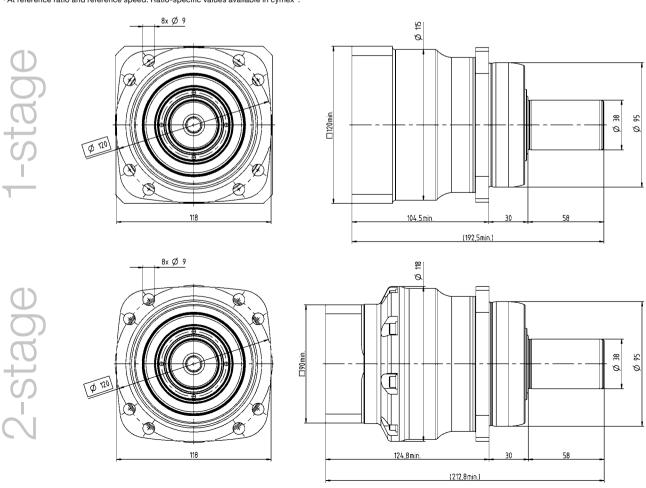
<sup>a) Application-specific design with cymex® – www.wittenstein-cymex.com
b) For higher ambient temperatures, please reduce input speed
c) At reference ratio and reference speed. Ratio-specific values available in cymex®.</sup>



XP* 030 MF 1-/2-stage

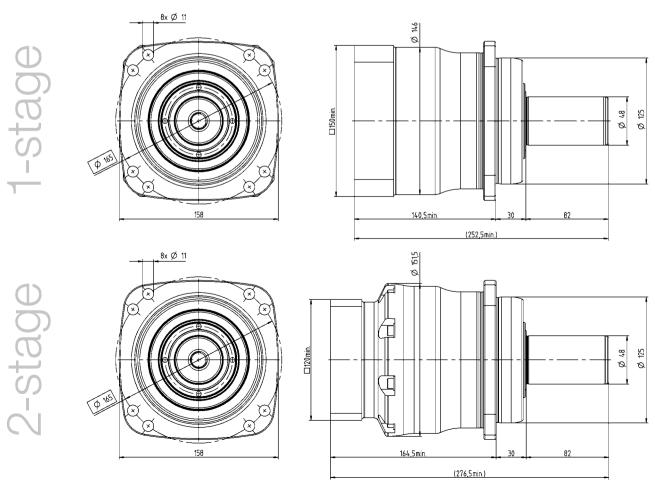
			1-stage	2-stage
Ratio	i		3/4/5/7/8/10	16 / 20 / 25 / 28 / 32 / 35 / 40 / 50 / 64 / 70 / 100
May tayaya a	т.	Nm	388 – 600	363 – 660
Max. torque ^{a)}	$T_{2\alpha}$	in.lb	3434 – 5310	3213 – 5842
Max. acceleration torque	_	Nm	320 – 550	303 – 550
(max. 1000 cycles per hour)	1 2B	in.lb	2832 – 4868	2682 – 4868
Nominal torque	т.	Nm	131 – 174	242 – 319
(at n _{1N})	1 2N	$T_{2B} \qquad \qquad \begin{array}{c} in.lb \\ \hline \\ T_{2N} \qquad & \\ \hline \\ T_{2Not} \qquad & \\ \hline \\ T_{2Not} \qquad & \\ \hline \\ T_{2Not} \qquad & \\ \hline \\ n_{nlb} \qquad & \\ \hline \\ n_{TT} \qquad & \\ \hline \\ rpm \qquad & \\ \hline \\ n_{1Max} \qquad & \\ \hline \\ rpm \qquad & \\ \hline \end{array}$	1157 – 1538	2142 – 2826
Emergency stop torque	т	Nm	650 – 900	750 – 1125
(permitted 1000 times during the service life of the gearbox)	1 _{2Not}	$ T_{2N} = \frac{in.lb}{in.lb} $ $ T_{2Not} = \frac{Nm}{in.lb} $ $ n_{1T} = rpm $ $ n_{1Max} = rpm $	5753 – 7966	6638 – 9957
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) b)	n _{1T}	rpm	2500 – 2800	3100 – 4200
Max. input speed	n _{1Max}	rpm	5500	6500
Max. torsional backlash	j_t	arcmin	Standard ≤ 3 / Reduced ≤ 1	Standard ≤ 4 / Reduced ≤ 2
Taraianal rigidity	0	Nm/arcmin	32 – 40	35 – 45
Torsional rigidity	C _{t21}	in.lb/arcmin	283 – 354	310 – 398
May Ailling manned	14	Nm	1296	1296
Max. tilting moment	M _{2KMax}	in.lb	11471	11471
Operating noise c)	L _{PA}	dB(A)	≤ 59	≤ 56
Lubrication			Lubricated for life	Lubricated for life
Clamping hub diameter		mm	19 – 38	14 – 28

a) Application-specific design with cymex® – www.wittenstein-cymex.com
 b) For higher ambient temperatures, please reduce input speed
 c) At reference ratio and reference speed. Ratio-specific values available in cymex®.



			1-stage	2-stage
Ratio	i		3/4/5/7/8/10	16 / 20 / 25 / 28 / 32 / 35 / 40 / 50 / 64 / 70 / 100
Max. torque a	т	Nm	792 – 1312	792 – 1188
wax. torque →	T_{2a}	in.lb	7010 – 11612	7010 – 10515
Max. acceleration torque	_	Nm	710 – 1080	660 – 990
(max. 1000 cycles per hour)	T _{2B}	in.lb	6284 – 9559	5842 – 8762
Nominal torque		Nm	202 – 335	461 – 607
(at n_m)	T _{2N}	T _{2Not} in.lb Nm in.lb	1786 – 2962	4078 – 5370
Emergency stop torque		Nm	1375 – 2310	1375 – 2310
(permitted 1000 times during the service life of the gearbox)	2Not	Tour	12170 – 20449	12170 – 20449
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) b)	n _{1T}	rpm	2100 – 2600	2900 – 3900
Max. input speed	n _{1Max}	rpm	5000	6000
Max. torsional backlash	j_t	arcmin	Standard ≤ 3 / Reduced ≤ 1	Standard ≤ 4 / Reduced ≤ 2
Torsional rigidity	6	Nm/arcmin	62 – 85	75 – 95
Torsional rigidity	C ₁₂₁	in.lb/arcmin	549 – 752	664 – 841
Max. tilting moment	14	Nm	1635	1635
wax. titting moment	M _{2KMax}	in.lb	14471	14471
Operating noise c)	L _{PA}	dB(A)	≤ 60	≤ 57
Lubrication			Lubricated for life	Lubricated for life
Clamping hub diameter		mm	24 – 48	19 – 38

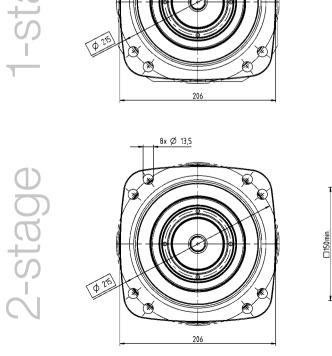
<sup>a) Application-specific design with cymex® – www.wittenstein-cymex.com
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c) At reference ratio and reference speed. Ratio-specific values available in cymex®.</sup>

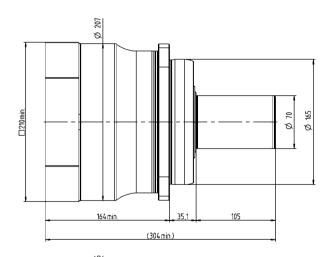


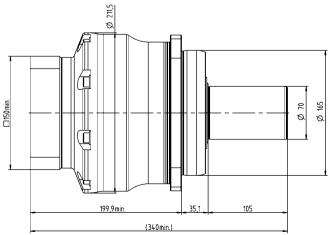
XP* 050 MF 1-/2-stage

			1-stage	2-stage
Ratio	i		3/4/5/7/8/10	16 / 20 / 25 / 28 / 32 / 35 / 40 / 50 / 64 / 70 / 100
Mary tangents 2)		Nm	2400 – 3840	1980 – 3696
Max. torque a)	1 2a	in.lb	21242 – 33987	17525 – 32713
Max. acceleration torque	7	Nm	1800 – 3360	1650 – 3080
(max. 1000 cycles per hour)	1 2B	in.lb	15931 – 29739	14604 – 27260
Nominal torque	_	Nm	513 – 927	1179 – 1505
(at n,,)	1 2N	in.lb	4544 – 8203	10426 – 13323
Emergency stop torque	_	Nm	3445 – 5000	3505 – 5000
(permitted 1000 times during the service life of the gearbox)	¹ 2Not	in.lb Nm in.lb Nm in.lb Nm in.lb Nm in.lb rpm rpm arcmin Nm/arcmin in.lb/arcmin	30493 – 44254	31022 – 44254
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) b)	n _{1T}	rpm	1500 – 2300	2700 – 3400
Max. input speed	n _{1Max}	rpm	4500	5000
Max. torsional backlash	j_t	arcmin	Standard ≤ 3 / Reduced ≤ 1	Standard ≤ 4 / Reduced ≤ 2
Torsional rigidity	0	Nm/arcmin	160 – 250	240 – 290
Torsional rigidity	C _{t21}	in.lb/arcmin	1416 – 2213	2124 – 2567
Max. tilting moment	Δ4	Nm	3256	3256
wax. tilting moment	IVI _{2KMax}	$ T_{2a} \qquad \qquad \begin{array}{c} In.lb \\ In.$	28818	28818
Operating noise ^{c)}	L_{PA}	dB(A)	≤ 64	≤ 58
Lubrication			Lubricated for life	Lubricated for life
Clamping hub diameter		mm	38 – 55	24 – 48

8x Ø 13,5





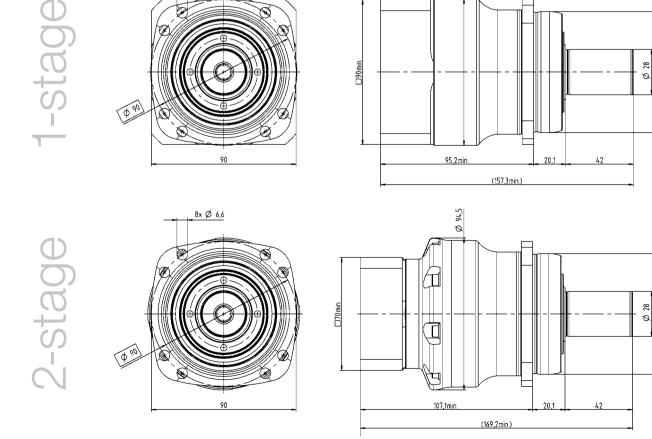


a) Application-specific design with cymex® – www.wittenstein-cymex.com
 b) For higher ambient temperatures, please reduce input speed
 c) At reference ratio and reference speed. Ratio-specific values available in cymex®.

			1-stage	2-stage
Ratio	i		3/4/5/7/8/10	16 / 20 / 25 / 28 / 32 / 35 / 40 / 50 / 64 / 70 / 100
Max. torque a)	_	Nm	68 – 90	70 – 90
Max. torque	T_{2a}	in.lb	602 – 797	620 – 797
Max. acceleration torque		Nm	68 – 90	70 – 90
(max. 1000 cycles per hour)	1 2B	in.lb	602 – 797	620 – 797
Nominal torque	_	Nm	41 – 53	56 – 72
(at n _m)	1 2N	$T_{2N} = \frac{Nm}{in.lb}$ $T_{2Not} = \frac{Nm}{in.lb}$ $n_{1T} = rpm$ $n_{1Max} = rpm$	362 – 468	496 – 637
Emergency stop torque	Tour	Nm	325 – 390	325 – 418
(permitted 1000 times during the service life of the gearbox)	1 _{2Not}	$T_{2Not} \qquad \frac{Nm}{in.lb}$ $n_{1T} \qquad rpm$	2877 – 3452	2877 – 3696
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) b)	n _{1T}	rpm	4500	4500
Max. input speed	n _{1Max}	rpm	6000	6000
Max. torsional backlash	j_t	arcmin	Standard ≤ 6 / Reduced ≤ 4	Standard ≤ 8 / Reduced ≤ 6
Torsional rigidity	0	Nm/arcmin	14 – 17	15 – 20
Torsional rigidity	C ₁₂₁	in.lb/arcmin	124 – 150	133 – 177
Max. tilting moment	14	Nm	675	675
Max. titting moment	M _{2KMax}	in.lb	5974	5974
Operating noise c)	L _{PA}	dB(A)	≤ 56	≤ 53
Lubrication			Lubricated for life	Lubricated for life
Clamping hub diameter		mm	19 – 24	14 – 19

8

8x Ø 6,6

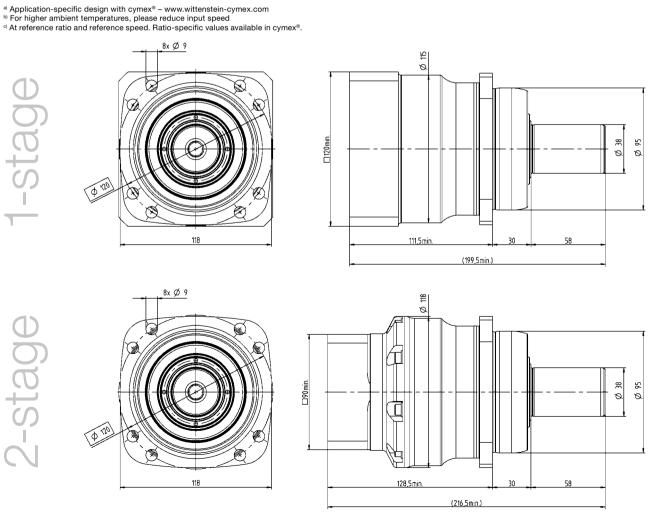


Ø 75

<sup>a) Application-specific design with cymex® – www.wittenstein-cymex.com
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c) At reference ratio and reference speed. Ratio-specific values available in cymex®.</sup>

XP* 030 MC 1-/2-stage

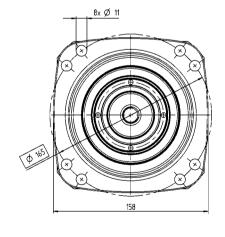
			1-stage	2-stage
Ratio	i		3/4/5/7/8/10	16 / 20 / 25 / 28 / 32 / 35 / 40 / 50 / 64 / 70 / 100
Mary house 2)	_	Nm	180 – 240	180 – 240
Max. torque a)	1 2a	in.lb	1593 – 2124	1593 – 2124
Max. acceleration torque	_	Nm	180 – 240	180 – 240
(max. 1000 cycles per hour)	1 2B	in.lb	1593 – 2124	1593 – 2124
Nominal torque	_	Nm	76 – 97	138 – 189
(at n _{nN})	1 2N	in.lb	677 – 861	1221 – 1673
Emergency stop torque	_	Nm	650 – 900	750 – 1125
(permitted 1000 times during the service life of the gearbox)	¹ 2Not	in.lb Nm in.lb Nm in.lb Nm in.lb Nm in.lb rpm rpm rpm arcmin Nm/arcmin in.lb/arcmin	5753 – 7966	6638 – 9957
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) b)	n _{1T}	rpm	3500 – 4500	4500
Max. input speed	n _{1Max}	rpm	6000	6000
Max. torsional backlash	j_t	arcmin	Standard ≤ 4 / Reduced ≤ 2	Standard ≤ 6 / Reduced ≤ 4
Torsional rigidity		Nm/arcmin	32 – 40	35 – 45
Torsional rigidity	C _{t21}	in.lb/arcmin	283 – 354	310 – 398
Max. tilting moment	Δ4	Nm	1296	1296
iviax. tilting moment	IVI _{2KMax}	$T_{2a} = \frac{Nm}{in.lb}$ $T_{2B} = \frac{Nm}{in.lb}$ $T_{2N} = \frac{Nm}{in.lb}$ $T_{2Not} = \frac{Nm}{in.lb}$ $T_{2Not} = \frac{Nm}{in.lb}$ $T_{2Not} = \frac{Nm}{in.lb}$ $T_{1T} = rpm$ $T_{1Max} = rpm$ $I_{t} = arcmin$ $I_{t} = arcmin$ $C_{t21} = \frac{Nm/arcmin}{in.lb/arcmin}$ $I_{t} = \frac{Nm/arcmin}{in.lb/arcmin}$ $I_{t} = \frac{Nm}{in.lb}$ I_{t	11471	11471
Operating noise ^{c)}	L _{PA}	dB(A)	≤ 59	≤ 56
Lubrication			Lubricated for life	Lubricated for life
Clamping hub diameter		mm	24 – 38	19 – 24

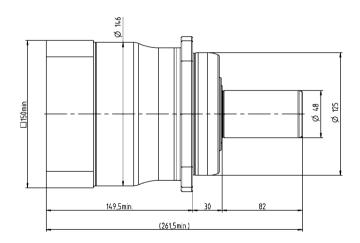


			1-stage	2-stage
Ratio	i		3/4/5/7/8/10	16 / 20 / 25 / 28 / 32 / 35 / 40 / 50 / 64 / 70 / 100
Mary Agrange (1)		Nm	310 – 480	380 – 480
Max. torque ^{a)}	/ _{2a}	in.lb	2744 – 4248	3363 – 4248
Max. acceleration torque	7	Nm	310 – 480	380 – 480
(max. 1000 cycles per hour)	1 _{2B}	in.lb	2744 – 4248	3363 – 4248
Nominal torque	7	Nm	127 – 195	277 – 367
$(at n_m)$	1 _{2N}	in.lb	1122 – 1730	2447 – 3250
Emergency stop torque	T	Nm	1375 – 2310	1375 – 2310
(permitted 1000 times during the service life of the gearbox)	1 _{2Not}	in.lb	12170 – 20445	12170 – 20445
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) b)	n _{1T}	rpm	3000 – 4500	4500
Max. input speed	n _{1Max}	rpm	6000	6000
Max. torsional backlash	j_t	arcmin	Standard ≤ 4 / Reduced ≤ 2	Standard ≤ 6 / Reduced ≤ 4
Taurianal visidita		Nm/arcmin	62 – 85	75 – 95
Torsional rigidity	C _{t21}	in.lb/arcmin	549 – 752	664 – 841
Mary Ailding magnet	44	Nm	1635	1635
Max. tilting moment	IVI _{2KMax}	$T_{2a} = \begin{array}{c} Nm \\ in.lb \\ Nm \\ in.lb \\ \\ T_{2B} = \begin{array}{c} Nm \\ in.lb \\ \\ Nm \\ in.lb \\ \\ T_{2Not} = \begin{array}{c} Nm \\ in.lb \\ \\ Nm \\ in.lb \\ \\ \\ T_{2Not} = \begin{array}{c} Nm \\ in.lb \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\$	14471	14471
Operating noise c)	L _{PA}	dB(A)	≤ 60	≤ 57
Lubrication			Lubricated for life	Lubricated for life
Clamping hub diameter		mm	38 – 48	24 – 38

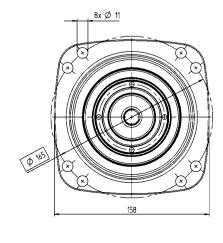
<sup>a) Application-specific design with cymex® – www.wittenstein-cymex.com
b) For higher ambient temperatures, please reduce input speed
c) At reference ratio and reference speed. Ratio-specific values available in cymex®.</sup>

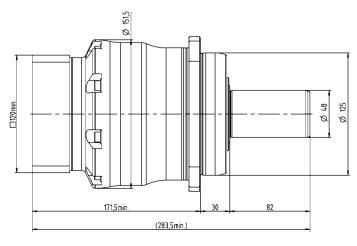








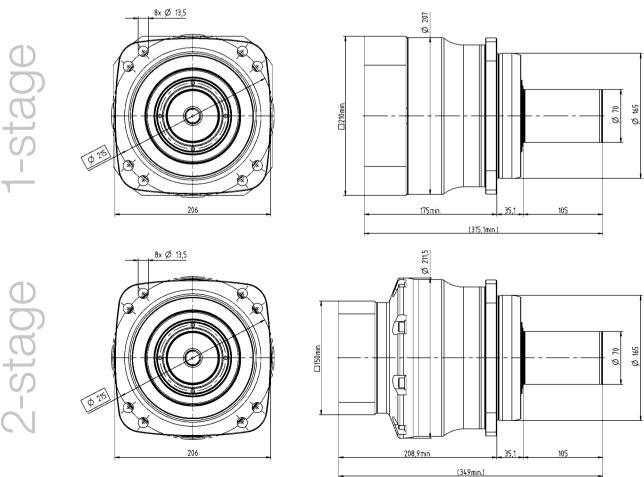




XP* 050 MC 1-/2-stage

			1-stage	2-stage
Ratio	i		3/4/5/7/8/10	16 / 20 / 25 / 28 / 32 / 35 / 40 / 50 / 64 / 70 / 100
Max. torque a)	7	Nm	700 – 880	700 – 880
Max. torque -	$T_{2\alpha}$	in.lb	6196 – 7789	6196 – 7789
Max. acceleration torque	_	Nm	700 – 880	700 – 880
(max. 1000 cycles per hour)	T _{2B}	in.lb	6196 – 7789	6196 – 7789
Nominal torque		Nm	289 – 492	560 – 704
(at n,,,)	1 _{2N}	T _{2N} in.lb Nm T _{2Not} in.lb	2554 – 4355	4956 – 6231
Emergency stop torque	7	Nm	3445 – 5000	3505 – 5000
(permitted 1000 times during the service life of the gearbox)	¹ 2Not	T _{au} .	30493 – 44254	31022 – 44254
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) ^{b)}	n _{1T}	rpm	3000 – 4500	4500
Max. input speed	n _{1Max}	rpm	4500 – 6000	6000
Max. torsional backlash	j_t	arcmin	Standard ≤ 4 / Reduced ≤ 2	Standard ≤ 6 / Reduced ≤ 4
Taraianal rigidity		Nm/arcmin	160 – 250	240 – 290
Torsional rigidity	C ₁₂₁	in.lb/arcmin	1416 – 2213	2124 – 2567
NACY Allies records		Nm	3256	3256
Max. tilting moment	M _{2KMax}	in.lb	28818	28818
Operating noise c)	L _{PA}	dB(A)	≤ 64	≤ 58
Lubrication			Lubricated for life	Lubricated for life
Clamping hub diameter		mm	48	38

a) Application-specific design with cymex® – www.wittenstein-cymex.com
 b) For higher ambient temperatures, please reduce input speed
 c) At reference ratio and reference speed. Ratio-specific values available in cymex®.







RP+ - The high-precision powerhouse



Product highlights

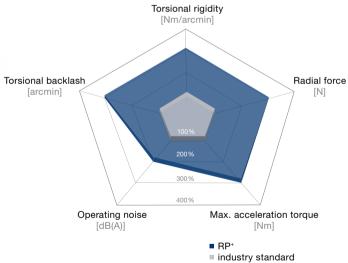
Max. torsional backlash [arcmin] ≤ 1 – 3 High axial and radial forces Easy installation Optimized for rack and pinion applications This gearbox series sets standards in terms of power density, modularity and easy installation. It is used in all applications where the individual requirements far exceed what has previously been possible. RP+ gearboxes combine all the advantages of the familiar gearbox series:

- · Reduced backlash of ≤ 1 arcmin
- · Maximum power density
- · Extremely smooth-running thanks to helical toothing
- · Maximum positioning accuracy and world-class lifespan

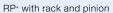
The RP+ impresses with maximum power density

- · if your drive requires maximum performance
- · if you value world-class engineering
- · if you require an even more compact system

The RP+ compared to the industry standard









RPK+ with hypoid angle section

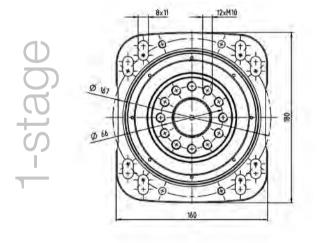


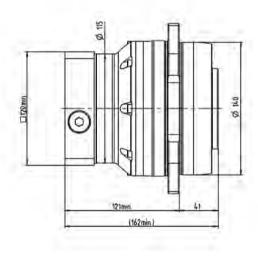


RP* 030 MF 1-stage

			1-stage
Ratio	i		4/5/7/10
		Nm	352 – 380
Max. torque ^{a)}	T _{2a}	in.lb	3115 – 3363
Max. acceleration torque	_	Nm	318 – 380
(max. 1000 cycles per hour)	T _{2B}	in.lb	2815 – 3363
Nominal torque		Nm	172 – 182
(at n _{1,h})	T _{2N}	in.lb	1522 – 1611
Emergency stop torque		Nm	625
(permitted 1000 times during the service life of the gearbox)	T _{2Not}	in.lb	5532
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) ^{ISI}	n _{1T}	rpm	2000 – 2800
Max. input speed	n _{1Max}	rpm	5500
Max. torsional backlash	j_t	arcmin	Standard ≤ 3 / Reduced ≤ 1
Torsional rigidity		Nm/arcmin	62 – 86
Torsional rigidity	C _{t21}	in.lb/arcmin	549 – 761
Max. tilting moment	Λ4	Nm	1800
wax. uiting moment	M _{2KMax}	in.lb	15931
Operating noise ^{c)}	L _{PA}	dB(A)	≤ 61
Lubrication			Lubricated for life
Clamping hub diameter		mm	19 – 38

<sup>a) Application-specific design with cymex® – www.wittenstein-cymex.com
b) For higher ambient temperatures, please reduce input speed
c) At reference ratio and reference speed. Ratio-specific values available in cymex®.</sup>

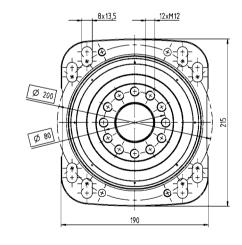


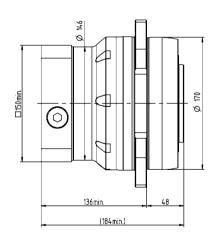


			1-stage
Ratio	i		4/5/7/10
May tagging a)		Nm	720 – 1120
Max. torque ^{a)}	T_{2a}	in.lb	6373 – 9913
Max. acceleration torque		Nm	540 – 700
(max. 1000 cycles per hour)	T _{2B}	in.lb	4779 – 6196
Nominal torque	_	Nm	272 – 318
(at $n_{_{\mathcal{N}}}$)	T_{2N}	in.lb	2408 – 2810
Emergency stop torque	_	Nm	1563
rmitted 1000 times during the service life of the gearbox)	T_{2Not}	in.lb	13829
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) b)	n _{1T}	rpm	2500 – 3200
Max. input speed	n _{1Max}	rpm	5000
Max. torsional backlash	j_t	arcmin	Standard ≤ 3 / Reduced ≤ 1
Taraianal rigidity	0	Nm/arcmin	123 – 190
Torsional rigidity	C ₁₂₁	in.lb/arcmin	1089 – 1682
May Alking magnet		Nm	3600
Max. tilting moment	M _{2KMax}	in.lb	31863
Operating noise ©	L _{PA}	dB(A)	≤ 61
Lubrication			Lubricated for life
Clamping hub diameter		mm	24 – 48

<sup>a) Application-specific design with cymex® – www.wittenstein-cymex.com
b) For higher ambient temperatures, please reduce input speed
c) At reference ratio and reference speed. Ratio-specific values available in cymex®.</sup>



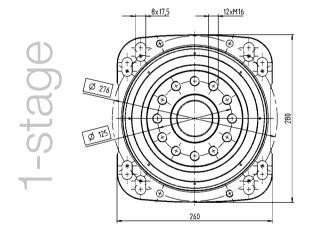


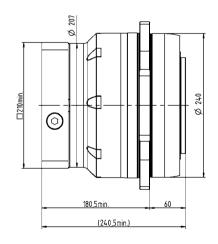


RP+ **050 MF** 1-stage

			1-stage
Ratio	i		4/5/7/10
Mary Agreeme (1)		Nm	2240 – 2560
Max. torque ^{a)}	$T_{2\alpha}$	in.lb	19826 – 22658
Max. acceleration torque	_	Nm	1400 – 1600
(max. 1000 cycles per hour)	T _{2B}	in.lb	12391 – 14161
Nominal torque	_	Nm	725 – 927
(at n _{1N})	T _{2N}	in.lb	6419 – 8203
Emergency stop torque	_	Nm	3204 – 3438
(permitted 1000 times during the service life of the gearbox)	T _{2Not}	in.lb	28357 – 30425
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) ^{b)}	n _{1T}	rpm	1500 – 2300
Max. input speed	n _{1Max}	rpm	4500
Max. torsional backlash	j_t	arcmin	Standard ≤ 3 / Reduced ≤ 1
Torsional rigidity		Nm/arcmin	445 – 610
Torsional rigidity	C _{t21}	in.lb/arcmin	3939 – 5399
Max. tilting moment	N4	Nm	11000
Max. tilting moment	M _{2KMax}	in.lb	97359
Operating noise ^{c)}	L _{PA}	dB(A)	≤ 66
Lubrication			Lubricated for life
Clamping hub diameter		mm	38 – 48

<sup>a) Application-specific design with cymex® – www.wittenstein-cymex.com
b) For higher ambient temperatures, please reduce input speed
c) At reference ratio and reference speed. Ratio-specific values available in cymex®.</sup>







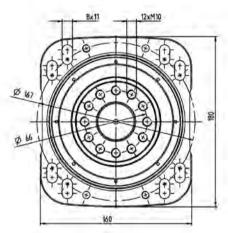


RP* 030 MA 1-/2-stage

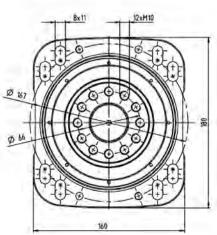
			1-stage	2-stage
Ratio	i		5.5	16 / 22 / 27.5 / 38.5 / 55
Mary Assessed all		Nm	583	583
Max. torque a)	$T_{2\alpha}$	in.lb	5160	5160
Max. acceleration torque		Nm	530	530
(max. 1000 cycles per hour)	T _{2B}	in.lb	4691	4691
Nominal torque	_	Nm	243	315 – 432
(at n _n)	T _{2N}	in.lb	2150	2788 – 3823
Emergency stop torque		Nm	1200	1200
(permitted 1000 times during the service life of the gearbox)	T _{2Not}	in.lb	10621	10621
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) b)	n _{1T}	rpm	2000	3000
Max. input speed	n _{1Max}	rpm	5500	7500
Max. torsional backlash	j_t	arcmin	Standard ≤ 1	Standard ≤ 1
Torsional rigidity	0	Nm/arcmin	105	100 – 105
Torsional rigidity	C _{t21}	in.lb/arcmin	929	885 – 929
Max. tilting moment	14	Nm	1800	1800
Max. titting moment	M _{2KMax}	in.lb	15931	15931
Operating noise ©	L _{PA}	dB(A)	≤ 65	≤ 58
Lubrication			Lubricated for life	Lubricated for life
Clamping hub diameter		mm	19 – 38	19 – 24

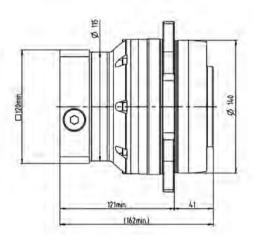
<sup>a) Application-specific design with cymex® – www.wittenstein-cymex.com
b) For higher ambient temperatures, please reduce input speed
c) At reference ratio and reference speed. Ratio-specific values available in cymex®.</sup>

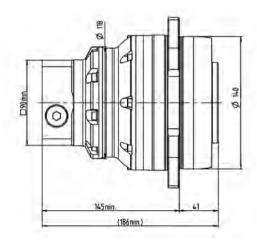








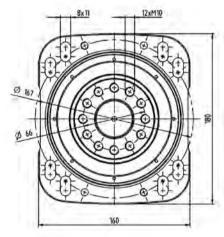


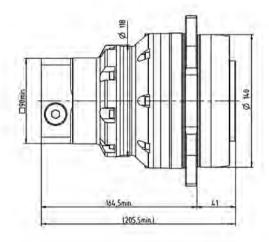


			3-stage
Ratio	i		66 / 88 / 110 / 154 / 220
Max. torque ^{a)}	т	Nm	583
wax. torque -	T _{2a}	in.lb	5160
Max. acceleration torque	_	Nm	530
(max. 1000 cycles per hour)	T _{2B}	in.lb	4691
Nominal torque	-	Nm	284 – 397
(at n,,)	T _{2N}	in.lb	2513 – 3513
Emergency stop torque	_	Nm	1200
Emergency stop torque (permitted 1000 times during the service life of the gearbox)	T _{2Not}	in.lb	10621
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) b)	n _{1T}	rpm	3000
Max. input speed	n _{1Max}	rpm	7500
Max. torsional backlash	j_t	arcmin	Standard ≤ 1
Tausian at visialita	0	Nm/arcmin	95
Torsional rigidity	C ₁₂₁	in.lb/arcmin	841
May tilting moment	14	Nm	1800
Max. tilting moment	M _{2KMax}	in.lb	15931
Operating noise c)	L _{PA}	dB(A)	≤ 56
Lubrication			Lubricated for life
Clamping hub diameter		mm	19

- a) Application-specific design with cymex® www.wittenstein-cymex.com
 b) For higher ambient temperatures, please reduce input speed
 c) At reference ratio and reference speed. Ratio-specific values available in cymex®.



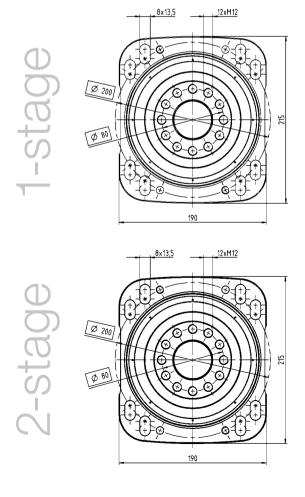


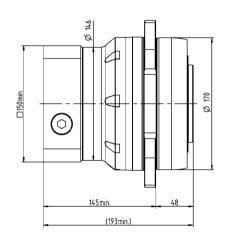


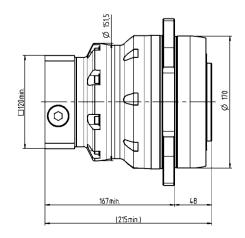
RP* 040 MA 1-/2-stage

			1-stage	2-stage
Ratio	i		5.5	16 / 22 / 27.5 / 38.5 / 55
Mary Assessed	-	Nm	1402	1270 – 1402
Max. torque ^{a)}	$T_{2\alpha}$	in.lb	12406	11243 – 12406
Max. acceleration torque	т	Nm	950	950
(max. 1000 cycles per hour)	T _{2B}	in.lb	8408	8408
Nominal torque	_	Nm	417	476 – 653
(at n_{η_0})	T_{2N}	in.lb	3695	4217 – 5779
Emergency stop torque		Nm	2865	2420 – 2613
(permitted 1000 times during the service life of the gearbox)	T _{2Not}	in.lb	25358	21416 – 25358
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) b)	$n_{_{1T}}$	rpm	2500	4000 – 4100
Max. input speed	n _{1Max}	rpm	5000	6250
Max. torsional backlash	j_t	arcmin	Standard ≤ 1	Standard ≤ 1
Torsional rigidity	0	Nm/arcmin	220	220
Torsional rigidity	C ₁₂₁	in.lb/arcmin	1947	1947
NACY Allaine recorded	14	Nm	3600	3600
Max. tilting moment	M _{2KMax}	in.lb	31863	31863
Operating noise c)	L _{PA}	dB(A)	≤ 63	≤ 61
Lubrication			Lubricated for life	Lubricated for life
Clamping hub diameter		mm	38 – 48	24 – 38

a) Application-specific design with cymex® – www.wittenstein-cymex.com
 b) For higher ambient temperatures, please reduce input speed
 c) At reference ratio and reference speed. Ratio-specific values available in cymex®.



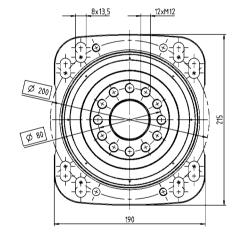


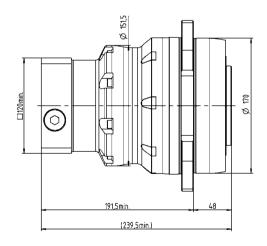


			3-stage
Ratio	i		66 / 88 / 110 / 154 / 220
May tagen a	<i>T</i>	Nm	1402
Max. torque ^{a)}	$T_{2\alpha}$	in.lb	12406
Max. acceleration torque	T	Nm	950
(max. 1000 cycles per hour)	T _{2B}	in.lb	8408
Nominal torque	T	Nm	690 – 760
$({\rm at} n_n)$	T _{2N}	in.lb	6103 – 6727
Emergency stop torque	T	Nm	2865
(permitted 1000 times during the service life of the gearbox)	T _{2Not}	in.lb	25358
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) b)	n _{1T}	rpm	4100
Max. input speed	n _{1Max}	rpm	6250
Max. torsional backlash	j_t	arcmin	Standard ≤ 1
Torsional rigidity	0	Nm/arcmin	205
Torsional rigidity	C _{t21}	in.lb/arcmin	1814
Max. tilting moment	14	Nm	3600
wax. utung moment	M _{2KMax}	in.lb	31863
Operating noise ©	L _{PA}	dB(A)	≤ 58
Lubrication			Lubricated for life
Clamping hub diameter		mm	24

<sup>a) Application-specific design with cymex® – www.wittenstein-cymex.com
b) For higher ambient temperatures, please reduce input speed
c) At reference ratio and reference speed. Ratio-specific values available in cymex®.</sup>



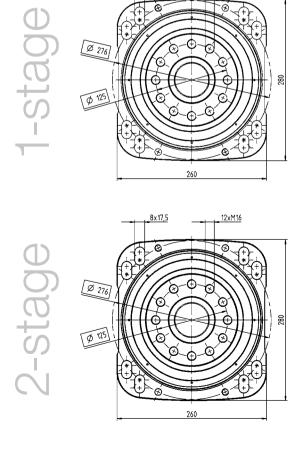


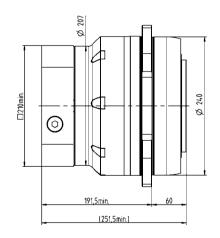


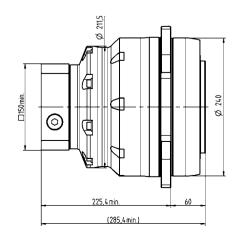
RP* 050 MA 1-/2-stage

			1-stage	2-stage
Ratio	i		5.5	16 / 22 / 27.5 / 38.5 / 55
Mary Assessed	-	Nm	3822	3518 – 3822
Max. torque ^{a)}	$T_{2\alpha}$	in.lb	33826	28323 – 33826
Max. acceleration torque	_	Nm	3100	2000 – 3100
(max. 1000 cycles per hour)	T _{2B}	in.lb	27437	17702 – 27437
Nominal torque	_	Nm	1167	1174 – 1977
(at n _{1N})	T_{2N}	in.lb	10326	10387 – 17501
Emergency stop torque		Nm	6250	7150
(permitted 1000 times during the service life of the gearbox)	T _{2Not}	in.lb	55318	63283
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) b)	$n_{_{1T}}$	rpm	1500	3100 – 3300
Max. input speed	n _{1Max}	rpm	4500	5625
Max. torsional backlash	j_t	arcmin	Standard ≤ 1	Standard ≤ 1
Torsional rigidity	0	Nm/arcmin	730	670 – 730
Torsional rigidity	C ₁₂₁	in.lb/arcmin	6461	5930 – 6461
Max. tilting moment	14	Nm	11000	11000
Max. titting moment	M _{2KMax}	in.lb	97359	97359
Operating noise c)	L _{PA}	dB(A)	≤ 66	≤ 64
Lubrication			Lubricated for life	Lubricated for life
Clamping hub diameter		mm	48	38 – 48

12xM16





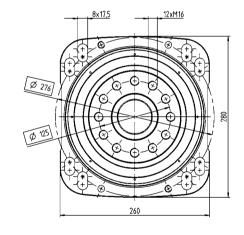


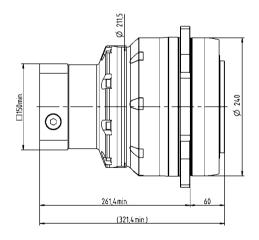
a) Application-specific design with cymex® – www.wittenstein-cymex.com
 b) For higher ambient temperatures, please reduce input speed
 c) At reference ratio and reference speed. Ratio-specific values available in cymex®. 8x 17,5

		I	
			3-stage
Ratio	i		66 / 88 / 110 / 154 / 220
Max. torque a)	T	Nm	3023
wax. torque	T _{2a}	in.lb	26757
Max. acceleration torque	T	Nm	2600
(max. 1000 cycles per hour)	T _{2B}	in.lb	23012
Nominal torque	_	Nm	1602 – 2080
(at n_n)	T _{2N}	in.lb	14182 – 18410
Emergency stop torque	_	Nm	8125
Emergency stop torque (permitted 1000 times during the service life of the gearbox)	T _{2Not}	in.lb	71913
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) ⁵⁰	n _{1T}	rpm	3300
Max. input speed	n _{1Max}	rpm	5625
Max. torsional backlash	j_t	arcmin	Standard ≤ 1
Torgianal vigidity	0	Nm/arcmin	650
Torsional rigidity	C ₁₂₁	in.lb/arcmin	5753
Max. tilting moment	14	Nm	11000
Max. tilting moment	M _{2KMax}	in.lb	97359
Operating noise ^{c)}	L _{PA}	dB(A)	≤ 59
Lubrication			Lubricated for life
Clamping hub diameter		mm	38

<sup>a) Application-specific design with cymex® – www.wittenstein-cymex.com
b) For higher ambient temperatures, please reduce input speed
c) At reference ratio and reference speed. Ratio-specific values available in cymex®.</sup>



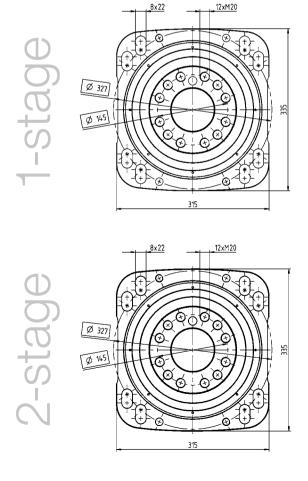


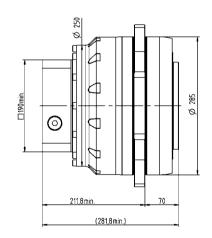


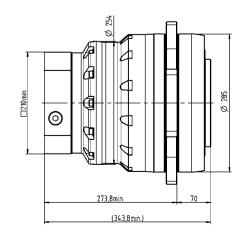
RP* 060 MA 1-/2-stage

			1-stage	2-stage
Ratio	i		5.5	22 / 27.5 / 38.5 / 55
May Agress 2	T	Nm	7360	6240 - 7535
Max. torque ^{a)}	$T_{2\alpha}$	in.lb	65142	55229 - 66691
Max. acceleration torque	_	Nm	4600	3900 – 5500
max. 1000 cycles per hour)	T_{2B}	in.lb	40714	34518 – 48679
Nominal torque	т.	Nm	2829	3120 – 3530
at n _n)	T_{2N}	in.lb	25035	27614 - 31243
Emergency stop torque	т	Nm	10938	15296 – 15333
permitted 1000 times during the service life of the gearbox)	T _{2Not}	in.lb	96806	135377 – 135709
Thermal speed limit with 20°C ambient temperature and 10% torque utilization) ^{b)}	$n_{_{1T}}$	rpm	1000	2750
Max. input speed	n _{1Max}	rpm	3125	4375
Max. torsional backlash	j_t	arcmin	Standard ≤ 1	Standard ≤ 1,5
Forsional rigidity	0	Nm/arcmin	1200	1200
orsional rigidity	C ₁₂₁	in.lb/arcmin	10621	10621
Any tilting mamont	14	Nm	21000	21000
Max. tilting moment	M _{2KMax}	in.lb	185867	185867
Operating noise ©	L _{PA}	dB(A)	≤ 68	≤ 64
ubrication			Lubricated for life	Lubricated for life
Clamping hub diameter		mm	55	48

a) Application-specific design with cymex® – www.wittenstein-cymex.com
 b) For higher ambient temperatures, please reduce input speed
 c) At reference ratio and reference speed. Ratio-specific values available in cymex®.



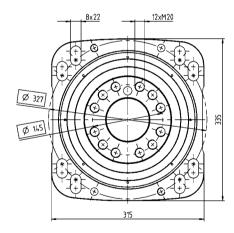


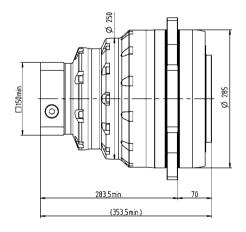


			3-stage
Ratio	i		66 / 88 / 110 / 154 / 220
Max. torque ^{a)}	T	Nm	6987
iviax. torque	T _{2a}	in.lb	61838
Max. acceleration torque		Nm	5500
(max. 1000 cycles per hour)	T _{2B}	in.lb	48679
Nominal torque		Nm	2923 – 4196
(at n _m)	T _{2N}	in.lb	25869 – 37136
Emergency stop torque		Nm	15333
(permitted 1000 times during the service life of the gearbox)	T _{2Not}	in.lb	135709
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) b)	n _{1T}	rpm	2750
Max. input speed	n _{1Max}	rpm	4375
Max. torsional backlash	j_t	arcmin	Standard ≤ 1,5
Torsional rigidity		Nm/arcmin	1200
Torsional rigidity	C _{t21}	in.lb/arcmin	10621
Max. tilting moment	14	Nm	21000
wax. titting moment	M _{2KMax}	in.lb	185867
Operating noise ©	L _{PA}	dB(A)	≤ 59
Lubrication			Lubricated for life
Clamping hub diameter		mm	38

<sup>a) Application-specific design with cymex® – www.wittenstein-cymex.com
b) For higher ambient temperatures, please reduce input speed
c) At reference ratio and reference speed. Ratio-specific values available in cymex®.</sup>



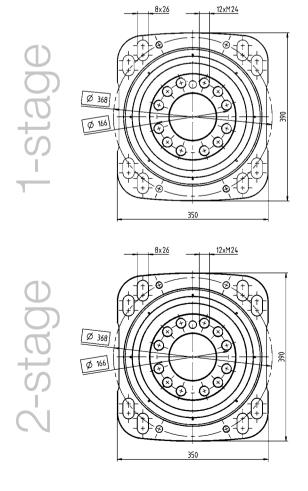


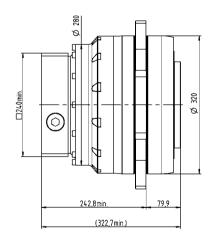


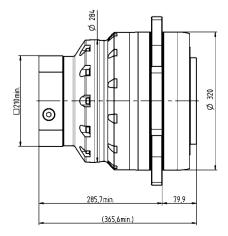
RP* 080 MA 1-/2-stage

			1-stage	2-stage
Ratio	i		5.5	22 / 27.5 / 38.5 / 55
Mary Assessed	T	Nm	10450	10450
Max. torque ^{a)}	$T_{2\alpha}$	in.lb	92491	92491
Max. acceleration torque	T	Nm	8000	7200 – 10000
max. 1000 cycles per hour)	T _{2B}	in.lb	70806	63726 – 88508
Nominal torque	_	Nm	4313	4602 – 4921
at $n_{_{IN}}$	T_{2N}	in.lb	38174	40736 – 43558
Emergency stop torque	_	Nm	18750	25000
permitted 1000 times during the service life of the gearbox)	T _{2Not}	in.lb	165953	221270
Thermal speed limit with 20°C ambient temperature and 10% torque utilization) ^{b)}	$n_{_{1T}}$	rpm	900	1950
Max. input speed	n _{1Max}	rpm	3125	4375
Max. torsional backlash	j_t	arcmin	Standard ≤ 1	Standard ≤ 1,5
Torsional rigidity	0	Nm/arcmin	2000	2000
orsional rigidity	C _{t21}	in.lb/arcmin	17702	17702
May tilting mamont		Nm	34000	34000
Max. tilting moment	M _{2KMax}	in.lb	300927	300927
Operating noise c)	L _{PA}	dB(A)	≤ 68	≤ 65
_ubrication			Lubricated for life	Lubricated for life
Clamping hub diameter		mm	60	48

a) Application-specific design with cymex® – www.wittenstein-cymex.com
 b) For higher ambient temperatures, please reduce input speed
 c) At reference ratio and reference speed. Ratio-specific values available in cymex®.



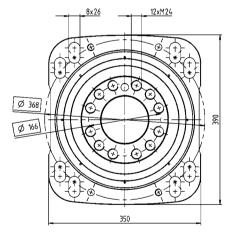


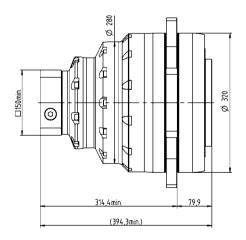


			3-stage
Ratio	i		66 / 88 / 110 / 154 / 220
May tagen a)		Nm	10450
Max. torque ^{a)}	T_{2a}	in.lb	92491
Max. acceleration torque	_	Nm	10000
(max. 1000 cycles per hour)	T _{2B}	in.lb	88508
Nominal torque	_	Nm	4567 – 7308
(at $n_{_{\mathcal{N}}}$)	T _{2N}	in.lb	40418 – 64684
Emergency stop torque	_	Nm	25000
(permitted 1000 times during the service life of the gearbox)	T _{2Not}	in.lb	221270
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) b)	n _{1T}	rpm	1950
Max. input speed	n _{1Max}	rpm	4375
Max. torsional backlash	j_t	arcmin	Standard ≤ 1,5
Torsional rigidity		Nm/arcmin	1800
Torsional rigidity	C ₁₂₁	in.lb/arcmin	15931
Max. tilting moment	14	Nm	34000
wax. uning moment	M _{2KMax}	in.lb	300927
Operating noise ©	L_{PA}	dB(A)	≤ 62
Lubrication			Lubricated for life
Clamping hub diameter		mm	38 – 48

<sup>a) Application-specific design with cymex® – www.wittenstein-cymex.com
b) For higher ambient temperatures, please reduce input speed
c) At reference ratio and reference speed. Ratio-specific values available in cymex®.</sup>











XPK⁺ and RPK⁺ hypoid gearboxes A new performance standard

XPK+/RPK+ - Power and precision in a compact design



New standard now also available as a hypoid version

Both the XP+ and RP+ Premium planetary gearboxes are now available in a right-angle version with hypoid gearing. The axis offset of hypoid gearboxes allows both higher ratios in one section (ratio i = 3 – 10) as well as higher torques compared to bevel gearboxes. The high torque density allows for an extremely compact, space-saving design. The mesh frequency and high torsional rigidity of the gearbox are also extremely impressive since they ensure a higher degree of positioning accuracy and extremely smooth operation.

XPK⁺ and RPK⁺ compared to industry standard

т

Max. torsional backlash

XPK⁺ ≤ 4 arcmin (Standard) ≤ 2 arcmin (Reduced)

RPK⁺ ≤ 1.3 arcmin

XPK+ and RPK+:

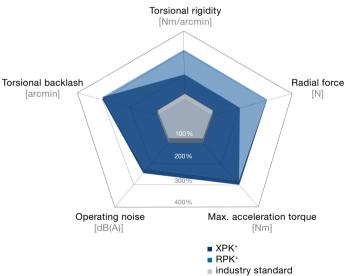
Range of transmission ratios: i = 12 - 5,500

High axial and radial forces

High torsional rigidity

Maximum performance in small installation space Optimized for rack and pinion applications

Product highlights





XPK+ with pinion and slots



XPK+ with pinion, slots and rack

The ideal partnership

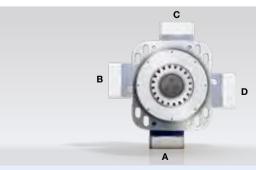
Premium Linear Systems with the XPK $^+$ or RPK $^+$ are used in all applications where the individual requirements far exceed what has previously been possible. Compared to the industry standard, the values of the RPK $^+$ have been improved by 150 % on average.

Integrated slots reduce the design and installation requirements to a minimum





RPK+ with rack and pinion

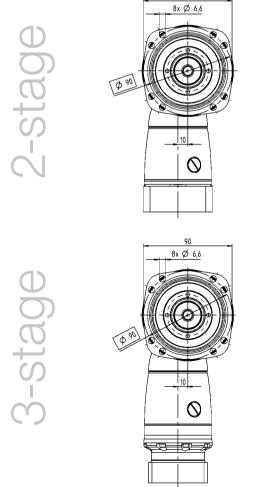


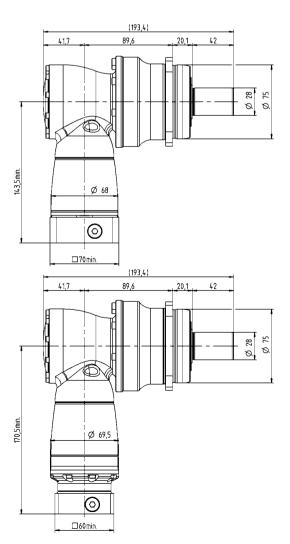
Flexibility during installation

XPK+ 020 MF 2-/3-stage

			2-stage	3-stage
Ratio	i		12 / 16 / 20 / 25 / 28 / 35 / 40 / 50 / 70 / 100	64 / 84 / 100 / 125 / 140 / 175 / 200 / 250 / 280 / 350 / 400 / 500 / 700 / 1000
May Assess al		Nm	80 – 240	80 – 240
Max. torque ^{a)}	T _{2a}	in.lb	708 – 2124	708 – 2124
Max. acceleration torque	_	Nm	80 – 180	80 – 180
(max. 1000 cycles per hour)	T_{2B}	in.lb	708 – 1593	708 – 1593
Nominal torque	7	Nm	60 – 75	60 – 90
(at n,,)	T_{2N}	in.lb	531 – 664	531 – 797
Emergency stop torque	_	Nm	160 – 350	160 – 350
(permitted 1000 times during the service life of the gearbox)	T _{2Not}	in.lb	1416 – 3098	1416 – 3098
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) b)	n _{tT}	rpm	3000 – 3800	5000 – 5500
Max. input speed	n _{1Max}	rpm	7500	6000
Max. torsional backlash	j_t	arcmin	Standard ≤ 5 / Reduced ≤ 3	Standard ≤ 5 / Reduced ≤ 3
Taraianal viaidity		Nm/arcmin	12 – 14	11 – 15
Torsional rigidity	C ₁₂₁	in.lb/arcmin	106 – 124	97 – 133
May Alking magnet	14	Nm	675	675
Max. tilting moment	M _{2KMax}	in.lb	5974	5974
Operating noise c)	L _{PA}	dB(A)	≤ 66	≤ 66
Lubrication			Lubricated for life	Lubricated for life
Clamping hub diameter		mm	14 – 19	11 – 14

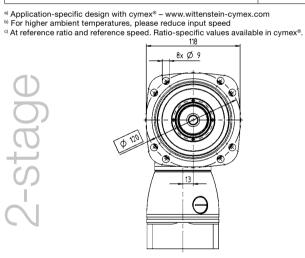
a) Application-specific design with cymex® – www.wittenstein-cymex.com
 b) For higher ambient temperatures, please reduce input speed
 c) At reference ratio and reference speed. Ratio-specific values available in cymex®.

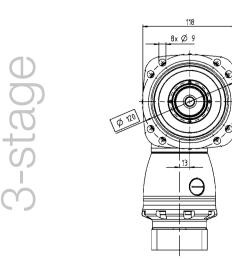


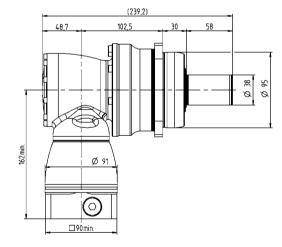


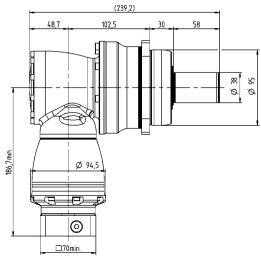
			2-stage	3-stage
Ratio	i		12 / 16 / 20 / 25 / 28 / 35 / 40 / 50 / 70 / 100	64 / 84 / 100 / 125 / 140 / 175 / 200 / 250 / 280 / 350 / 400 / 500 / 700 / 1000
Max. torque a	7	Nm	200 – 470	200 – 470
wax. torque →	$T_{2\alpha}$	in.lb	1770 – 4160	1770 – 4160
Max. acceleration torque		Nm	200 – 420	200 – 420
(max. 1000 cycles per hour)	T_{2B}	in.lb	1770 – 3717	1770 – 3717
Nominal torque	7	Nm	120 – 170	120 – 210
(at n_m)	T_{2N}	in.lb	1062 – 1505	1062 – 1859
Emergency stop torque		Nm	380 – 781	380 – 781
(permitted 1000 times during the service life of the gearbox)	T _{2Not}	in.lb	3363 – 6912	3363 – 6912
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) ^{b)}	n _{1T}	rpm	3000 – 3800	4500
Max. input speed	n _{1Max}	rpm	7500	6000
Max. torsional backlash	j_t	arcmin	Standard ≤ 4 / Reduced ≤ 2	Standard ≤ 4 / Reduced ≤ 2
Torsional rigidity	0	Nm/arcmin	29 – 36	29 – 36
Torsional rigidity	C _{t21}	in.lb/arcmin	257 – 319	257 – 319
Many Atlainer records	14	Nm	1296	1296
Max. tilting moment	M _{2KMax}	in.lb	11471	11471
Operating noise c)	$L_{\scriptscriptstyle PA}$	dB(A)	≤ 68	≤ 68
Lubrication			Lubricated for life	Lubricated for life
Clamping hub diameter		mm	19 – 28	14 – 19







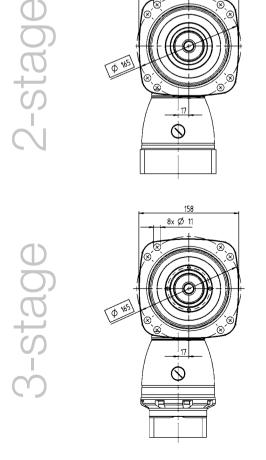


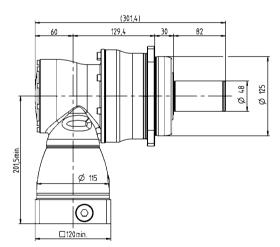


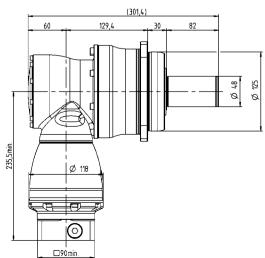
XPK+ 040 MF 2-/3-stage

			2-stage	3-stage
Ratio	i		12 / 16 / 20 / 25 / 28 / 35 / 40 / 50 / 70 / 100	64 / 84 / 100 / 125 / 140 / 175 / 200 / 250 / 280 / 350 / 400 / 500 / 700 / 1000
Max. torque a)	_	Nm	500 – 1020	500 – 1020
Max. torque 4	T _{2a}	in.lb	4425 – 9028	4425 – 9028
Max. acceleration torque	T	Nm	500 – 850	500 – 850
(max. 1000 cycles per hour)	T _{2B}	in.lb	4425 – 7523	4425 – 7523
Nominal torque	_	Nm	240 – 370	240 – 400
(at n,,)	T _{2N}	in.lb	2124 – 3275	2124 – 3540
Emergency stop torque	_	Nm	880 – 1820	880 – 1820
(permitted 1000 times during the service life of the gearbox)	T _{2Not}	in.lb	7789 – 16108	7789 – 16108
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) ^{b)}	n _{1T}	rpm	2700 – 3500	4000 – 4200
Max. input speed	n _{1Max}	rpm	5500	4500
Max. torsional backlash	j_t	arcmin	Standard ≤ 4 / Reduced ≤ 2	Standard ≤ 4 / Reduced ≤ 2
Tausianal visiality.	0	Nm/arcmin	60 – 77	60 – 77
Torsional rigidity	C ₁₂₁	in.lb/arcmin	531 – 682	531 – 682
May tilling magnet		Nm	1635	1635
Max. tilting moment	M _{2KMax}	in.lb	14471	14471
Operating noise c)	L _{PA}	dB(A)	≤ 70	≤ 70
Lubrication			Lubricated for life	Lubricated for life
Clamping hub diameter		mm	28 – 38	19 – 24

8x Ø 11

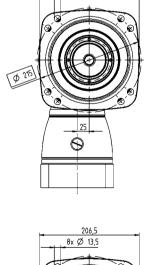






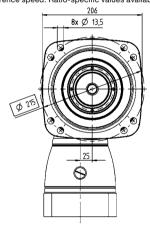
a) Application-specific design with cymex® – www.wittenstein-cymex.com
 b) For higher ambient temperatures, please reduce input speed
 c) At reference ratio and reference speed. Ratio-specific values available in cymex®.

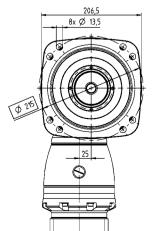
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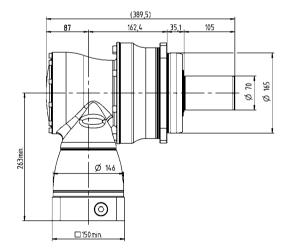


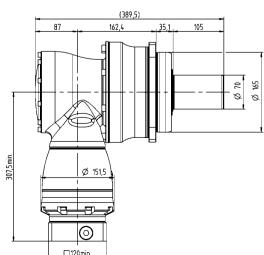
			2-stage	3-stage
Ratio	i		12 / 16 / 20 / 25 / 28 / 35 / 40 / 50 / 70 / 100	64 / 84 / 100 / 125 / 140 / 175 / 200 / 250 / 280 / 350 / 400 / 500 / 700 / 1000
Max. torque a)	т	Nm	840 – 2520	840 – 2520
Max. torque -	T_{2a}	in.lb	7435 – 22304	7435 – 22304
Max. acceleration torque	_	Nm	840 – 2100	840 – 2100
(max. 1000 cycles per hour)	T _{2B}	in.lb	7435 – 18587	7435 – 18587
Nominal torque	_	Nm	640 – 750	640 – 1250
(at n _m)	T _{2N}	in.lb	5665 – 6638	5665 – 11064
Emergency stop torque	_	Nm	1600 – 3505	1600 – 3505
(permitted 1000 times during the service life of the gearbox)	T _{2Not}	in.lb	14161 – 31022	14161 – 31022
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) b)	n _{1T}	rpm	2300 – 3000	4000 – 4200
Max. input speed	n _{1Max}	rpm	5000	4500
Max. torsional backlash	j_t	arcmin	Standard ≤ 4 / Reduced ≤ 2	Standard ≤ 4 / Reduced ≤ 2
Torsional rigidity		Nm/arcmin	176 – 224	176 – 226
Torsional rigidity	C ₁₂₁	in.lb/arcmin	1558 – 1983	1558 – 2000
Max. tilting moment		Nm	3256	3256
Max: utting moment	M _{2KMax}	in.lb	28818	28818
Operating noise c)	L _{PA}	dB(A)	≤ 71	≤ 70
Lubrication			Lubricated for life	Lubricated for life
Clamping hub diameter		mm	38	24 – 38
a) Application-specific design with cymex® – www.wittenstei	n-cymex com			

<sup>a) Application-specific design with cymex® – www.wittenstein-cymex.com
b) For higher ambient temperatures, please reduce input speed
c) At reference ratio and reference speed. Ratio-specific values available in cymex®.</sup>





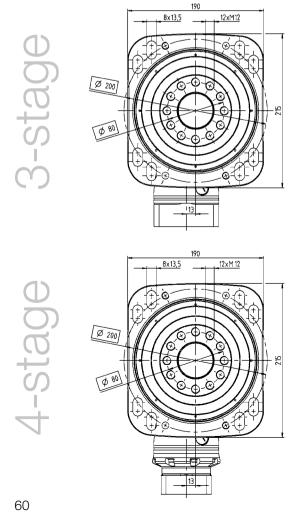


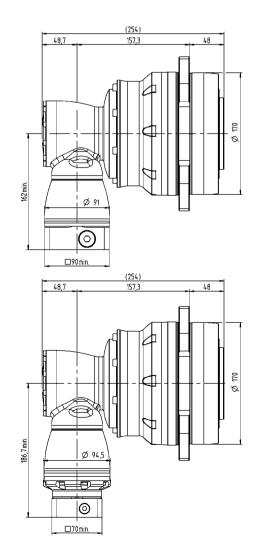


RPK+ 040 MA 3-/4-stage

			3-stage	4-stage
Ratio	i		48 / 66 / 88 / 110 / 137.5 / 154 / 220 / 385	330 / 462 / 577.5 / 770 / 1078 / 1540 / 2695 / 3850 / 5500
Max. torque a)		Nm	1100 – 1402	1402
wax. torque 4	$T_{2\alpha}$	in.lb	9736 – 12409	12409
Max. acceleration torque		Nm	950	950
(max. 1000 cycles per hour)	T _{2B}	in.lb	8408	8408
Nominal torque	_	Nm	675	675
(at n _{1N})	T _{2N}	in.lb	5974	5974
Emergency stop torque	_	Nm	1520 – 2613	2090 – 2613
rmitted 1000 times during the service life of the gearbox)	T _{2Not}	in.lb	13453 – 23127	18498 – 23127
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) ⁵⁾	n _{1T}	rpm	2800 – 3800	4300 – 4400
Max. input speed	n _{1Max}	rpm	7500	6000
Max. torsional backlash	j_t	arcmin	Standard ≤ 1,3	Standard ≤ 1,3
Torsional rigidity	0	Nm/arcmin	202 – 215	202 – 217
Torsional rigidity	C ₁₂₁	in.lb/arcmin	1788 – 1903	1788 – 1921
Max. tilting moment	A4	Nm	3600	3600
Max. tilting moment	M _{2KMax}	in.lb	31863	31863
Operating noise c)	L _{PA}	dB(A)	≤ 68	≤ 68
Lubrication			Lubricated for life	Lubricated for life
Clamping hub diameter		mm	19 – 28	14 – 19

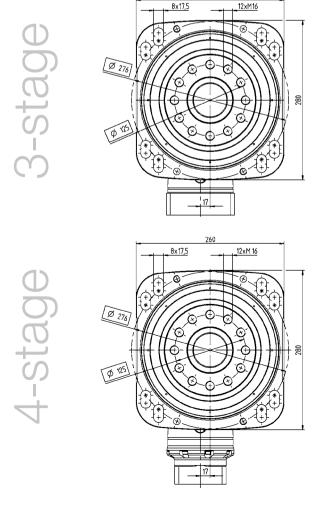
a) Application-specific design with cymex® – www.wittenstein-cymex.com
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 c) At reference ratio and reference speed. Ratio-specific values available in cymex®.

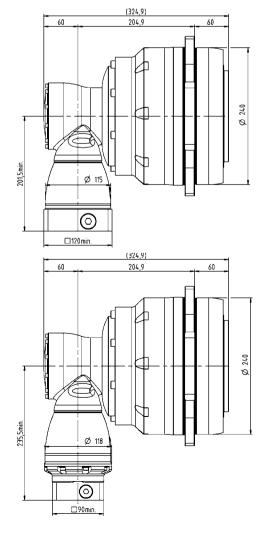




			3-stage	4-stage
Ratio	i		48 / 66 / 88 / 110 / 137.5 / 154 / 220 / 385	330 / 462 / 577.5 / 770 / 1078 / 1540 / 2695 / 3850 / 5500
May tayaya a)	T	Nm	2750 – 3822	3200 – 3822
Max. torque ^{a)}	$T_{2\alpha}$	in.lb	24340 – 33828	28323 – 33828
Max. acceleration torque	_	Nm	2720 – 3100	2000 – 3100
(max. 1000 cycles per hour)	T_{2B}	in.lb	24074 – 27437	17702 – 27437
Nominal torque	т.	Nm	1600 – 1650	1400 – 1650
(at n_m)	T_{2N}	in.lb	14161 – 14604	12391 – 14604
Emergency stop torque	т	Nm	3520 – 7150	4840 – 7150
(permitted 1000 times during the service life of the gearbox)	T _{2Not}	in.lb	31155 – 63283	42838 – 63283
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) ^{b)}	n _{1T}	rpm	2800 – 3600	3800 – 4100
Max. input speed	n _{1Max}	rpm	5500	4500
Max. torsional backlash	j_t	arcmin	Standard ≤ 1,3	Standard ≤ 1,3
Torsional vigidity	0	Nm/arcmin	634 – 687	634 – 689
Torsional rigidity	C _{t21}	in.lb/arcmin	5611 – 6080	5611 – 6098
May tilling pages	1.4	Nm	11000	11000
Max. tilting moment	M _{2KMax}	in.lb	97359	97359
Operating noise c)	L _{PA}	dB(A)	≤ 70	≤ 70
Lubrication			Lubricated for life	Lubricated for life
Clamping hub diameter		mm	28 – 38	19 – 24

<sup>a) Application-specific design with cymex® – www.wittenstein-cymex.com
b) For higher ambient temperatures, please reduce input speed
c) At reference ratio and reference speed. Ratio-specific values available in cymex®.</sup>



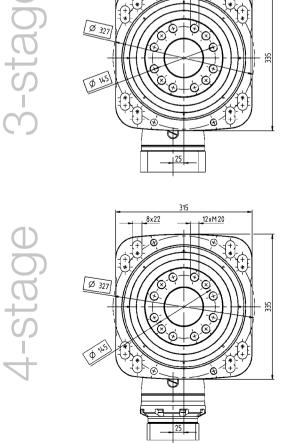


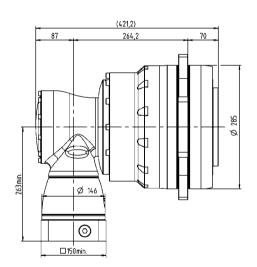
RPK+ 060 MA 3-/4-stage

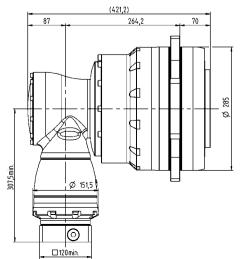
			3-stage	4-stage
Ratio	i		66 / 88 / 110 / 137.5 / 154 / 220 / 385	330 / 462 / 577.5 / 770 / 1078 / 1540 / 2695 / 3850 / 5500
Max. torque a)	т	Nm	4620 – 7535	6240 – 7535
Max. torque -	T _{2a}	in.lb	40891 – 66691	55229 – 66691
Max. acceleration torque	_	Nm	4620 – 5500	3900 – 5500
(max. 1000 cycles per hour)	T _{2B}	in.lb	30978 – 48679	34518 – 48679
Nominal torque	_T	Nm	3500	3500
$(at n_{i_N})$	T _{2N}	in.lb	30978	30978
Emergency stop torque	_	Nm	8800 – 14575	8800 – 14575
(permitted 1000 times during the service life of the gearbox)	T _{2Not}	in.lb	77887 – 129000	77887 – 129000
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) b)	n _{1T}	rpm	2300 – 2900	3800 – 4000
Max. input speed	n _{1Max}	rpm	5000	4500
Max. torsional backlash	j_t	arcmin	Standard ≤ 1,8	Standard ≤ 1,8
Torsional rigidity		Nm/arcmin	960 – 1114	953 – 1099
Torsional rigidity	C _{t21}	in.lb/arcmin	8497 – 9860	8435 – 9727
Max. tilting moment	A4	Nm	21000	21000
Max. titting moment	M _{2KMax}	in.lb	185867	185867
Operating noise a	L _{PA}	dB(A)	≤ 71	≤ 71
Lubrication			Lubricated for life	Lubricated for life
Clamping hub diameter		mm	38	24 – 38

8x22

12 xM 20



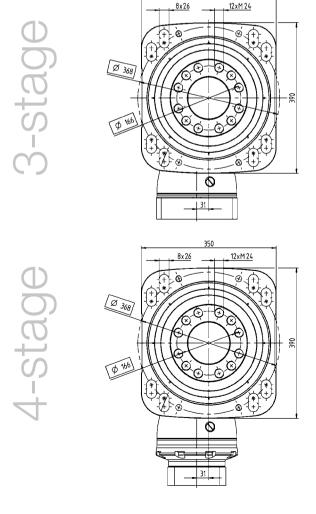


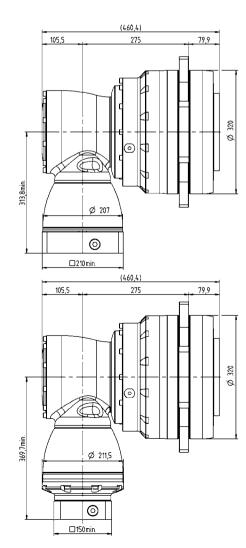


a) Application-specific design with cymex® – www.wittenstein-cymex.com
 b) For higher ambient temperatures, please reduce input speed
 c) At reference ratio and reference speed. Ratio-specific values available in cymex®.

			3-stage	4-stage
Ratio	i		66 / 88 / 110 / 137.5 / 154 / 220 / 385	330 / 462 / 577.5 / 770 / 1078 / 1540 / 2695 / 3850 / 5500
May targue a)	т	Nm	10340 – 10450	10450
Max. torque ^{a)}	$T_{2\alpha}$	in.lb	91517 – 92491	92491
Max. acceleration torque		Nm	10000	7200 – 10000
(max. 1000 cycles per hour)	T _{2B}	in.lb	88508	63726 – 88508
Nominal torque	_	Nm	5400	5400
(at n _m)	T _{2N}	in.lb	47794	47794
Emergency stop torque		Nm	19800 – 25000	19800 – 25000
ermitted 1000 times during the service life of the gearbox)	T _{2Not}	in.lb	175246 – 221270	175246 – 221270
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) ^{b)}	n _{1T}	rpm	1800 – 3100	3300 – 3600
Max. input speed	n _{1Max}	rpm	4500	4000
Max. torsional backlash	j_t	arcmin	Standard ≤ 1,8	Standard ≤ 1,8
Torsional rigidity	0	Nm/arcmin	1747 – 1901	1735 – 1879
Torsional rigidity	C _{t21}	in.lb/arcmin	15462 – 16825	15356 – 16631
Max. tilting moment	144	Nm	34000	34000
wax. titting moment	M _{2KMax}	in.lb	300927	300927
Operating noise ©	L _{PA}	dB(A)	≤ 71	≤ 71
Lubrication			Lubricated for life	Lubricated for life
Clamping hub diameter		mm	48	38 – 48

<sup>a) Application-specific design with cymex® – www.wittenstein-cymex.com
b) For higher ambient temperatures, please reduce input speed
c) At reference ratio and reference speed. Ratio-specific values available in cymex®.</sup>









XPC+/RPC+ - High precision and low ratios around the corner



New performance standard, also available in the bevel version

Both the XP+ and RP+ Premium planetary gearboxes are now available in a right-angle version with bevel toothing. Bevel gearboxes are primarily characterized by low gear ratios (ratio 1 and 2) in the angle section. Consequently, right-angle and planetary gearbox combinations can achieve the same low ratios as planetary gearboxes. The product design has a positive influence on temperature development in the gearbox and reduces overall heat development in the system as a result. The overall system achieves a higher degree of positioning accuracy as a consequence.

XPC+ and RPC+ compared to industry standard

Product highlights

Max. torsional backlash

XPC⁺ ≤ 4 arcmin (Standard) ≤ 2 arcmin (Reduced)

RPC⁺ ≤ 1.3 arcmin

XPC+ and RPC+:

Low ratios of i = 4 - 88 possible

Optimized temperature distribution, even at high speeds

High tilting moments and torsional rigidity Optimized for rack and pinion applications Torsional rigidity
[Nm/arcmin]

Torsional backlash

Radial force
[N]

Operating noise
[dB(A)]

XPC+

RPC
Industry standard



XPC+ with pinion and slots



XPC+ with pinion, slots and rack





RPC+ with pinion and slots



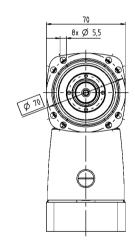
RPC+ with pinion, slots and rack

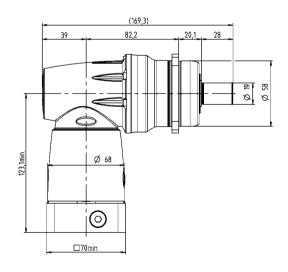
XPC+ 010 MF 2-stage

			2-stage
Ratio	i		4/5/7/8/10/14/20
May target al	T _{2a}	Nm	48 – 84
Max. torque a)		in.lb	425 – 743
Max. acceleration torque		Nm	40 – 70
(max. 1000 cycles per hour)	T _{2B}	in.lb	354 – 620
Nominal torque	T	Nm	27 – 28
(at n _{1/l})	T _{2N}	in.lb	239 – 248
Emergency stop torque	T	Nm	100 – 165
(permitted 1000 times during the service life of the gearbox)	T _{2Not}	in.lb	885 – 1460
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) ^{ts}	n _{1T}	rpm	3300 – 3750
Max. input speed	n _{1Max}	rpm	6000
Max. torsional backlash	j_t	arcmin	Standard ≤ 5 / Reduced ≤ 3
Torsional rigidity	0	Nm/arcmin	3.1 – 5,5
Torsional rigidity	C ₁₂₁	in.lb/arcmin	27 – 49
Max. tilting moment	M _{2KMax}	Nm	339
wax. uiting moment		in.lb	3000
Operating noise ^{c)}	L _{PA}	dB(A)	≤ 68
Lubrication			Lubricated for life
Clamping hub diameter		mm	14 – 19

<sup>a) Application-specific design with cymex® – www.wittenstein-cymex.com
b) For higher ambient temperatures, please reduce input speed
c) At reference ratio and reference speed. Ratio-specific values available in cymex®.</sup>



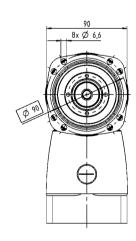


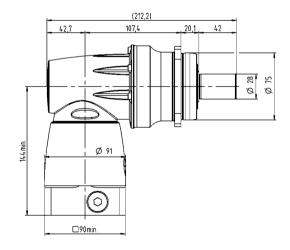


			2-stage
Ratio	i		4/5/7/8/10/14/20
Mary Assessed 2	T	Nm	144 – 240
Max. torque a)	$T_{2\alpha}$	in.lb	1275 – 2124
Max. acceleration torque	T	Nm	120 – 180
(max. 1000 cycles per hour)	T _{2B}	in.lb	1062 – 1593
Nominal torque	_	Nm	60 – 75
(at n _m)	T _{2N}	in.lb	531 – 664
Emergency stop torque	_	Nm	192 – 418
(permitted 1000 times during the service life of the gearbox)	T _{2Not}	in.lb	1699 – 3700
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) ^{b)}	$n_{_{1T}}$	rpm	2600 – 3050
Max. input speed	n _{1Max}	rpm	6000
Max. torsional backlash	j_t	arcmin	Standard ≤ 4 / Reduced ≤ 2
		Nm/arcmin	9.1 – 14
Torsional rigidity	C ₁₂₁	in.lb/arcmin	81 – 124
May tilling pages		Nm	675
Max. tilting moment	M _{2KMax}	in.lb	5974
Operating noise c)	L _{PA}	dB(A)	≤ 68
Lubrication			Lubricated for life
Clamping hub diameter		mm	19 – 28

<sup>a) Application-specific design with cymex® – www.wittenstein-cymex.com
b) For higher ambient temperatures, please reduce input speed
c) At reference ratio and reference speed. Ratio-specific values available in cymex®.</sup>





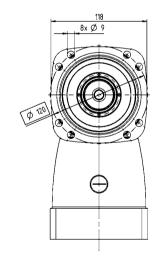


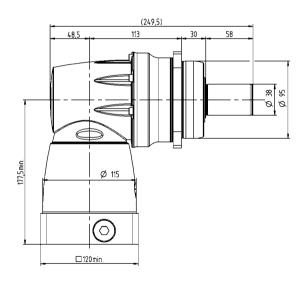
XPC+ 030 MF 2-stage

			2-stage
Ratio	i		4/5/7/8/10/14/20
May targue a	T _{2a}	Nm	389 – 486
Max. torque ^{a)}		in.lb	3443 – 4301
Max. acceleration torque	_	Nm	320 – 420
(max. 1000 cycles per hour)	T _{2B}	in.lb	2832 – 3717
Nominal torque		Nm	120 – 180
(at n _{1/l})	T _{2N}	in.lb	1062 – 1593
Emergency stop torque	T	Nm	540 – 800
(permitted 1000 times during the service life of the gearbox)	T _{2Not}	in.lb	4779 – 7081
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) ^{ISI}	n _{1T}	rpm	2100 – 2750
Max. input speed	n _{1Max}	rpm	4500
Max. torsional backlash	j_t	arcmin	Standard ≤ 4 / Reduced ≤ 2
Torsional visidity	C ₁₂₁	Nm/arcmin	23 – 36
Torsional rigidity		in.lb/arcmin	204 – 319
Max. tilting moment	M _{2KMax}	Nm	1296
wax. uiting moment		in.lb	11471
Operating noise ^{e)}	L _{PA}	dB(A)	≤ 68
Lubrication			Lubricated for life
Clamping hub diameter		mm	28 – 38

<sup>a) Application-specific design with cymex® – www.wittenstein-cymex.com
b) For higher ambient temperatures, please reduce input speed
c) At reference ratio and reference speed. Ratio-specific values available in cymex®.</sup>



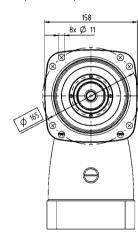


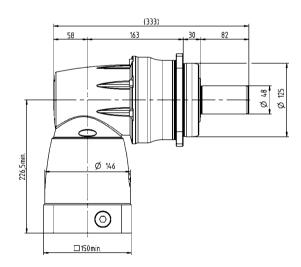


			2-stage
Ratio	i		4/5/7/8/10/14/20
	T _{2a}	Nm	792 – 1050
Max. torque ^{a)}		in.lb	7010 – 9293
Max. acceleration torque		Nm	700 – 875
(max. 1000 cycles per hour)	T_{2B}	in.lb	6196 – 7744
Nominal torque	_T	Nm	240 – 370
(at n _m)	T_{2N}	in.lb	2124 – 3275
Emergency stop torque	_	Nm	960 – 2170
(permitted 1000 times during the service life of the gearbox)	T _{2Not}	in.lb	8497 – 19206
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) ^{b)}	n _{1T}	rpm	1550 – 1900
Max. input speed	n _{1Max}	rpm	4500
Max. torsional backlash	j_t	arcmin	Standard ≤ 4 / Reduced ≤ 2
Tausian al disidita.		Nm/arcmin	50 – 74
Torsional rigidity	C ₁₂₁	in.lb/arcmin	443 – 655
May Alking magnet	.,	Nm	1635
Max. tilting moment	M _{2KMax}	in.lb	14471
Operating noise c)	L _{PA}	dB(A)	≤ 70
Lubrication			Lubricated for life
Clamping hub diameter		mm	38

<sup>a) Application-specific design with cymex® – www.wittenstein-cymex.com
b) For higher ambient temperatures, please reduce input speed
c) At reference ratio and reference speed. Ratio-specific values available in cymex®.</sup>





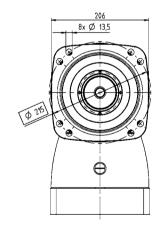


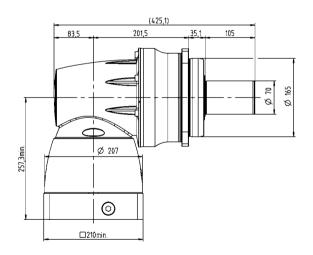
XPC+ 050 MF 2-stage

			2-stage
Ratio	i		4/5/7/8/10/14/20
	_	Nm	1512 – 2646
Max. torque ^{a)}	T _{2a}	in.lb	13382 – 23419
Max. acceleration torque	_	Nm	1260 – 2205
(max. 1000 cycles per hour)	T _{2B}	in.lb	11152 – 19516
Nominal torque	_	Nm	700 – 750
(at n _{1N})	T _{2N}	in.lb	6196 – 6638
Emergency stop torque	T	Nm	1560 – 4795
(permitted 1000 times during the service life of the gearbox)	T _{2Not}	in.lb	13807 – 42440
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) b)	n _{1T}	rpm	1050 – 1550
Max. input speed	n _{1Max}	rpm	4000
Max. torsional backlash	j_t	arcmin	Standard ≤ 4 / Reduced ≤ 2
Torsional rigidity	0	Nm/arcmin	127 – 215
Torsional rigidity	C ₁₂₁	in.lb/arcmin	1124 – 1903
Max. tilting moment	M _{2KMax}	Nm	3256
Max. titting moment		in.lb	28818
Operating noise c)	L _{PA}	dB(A)	≤ 70
Lubrication			Lubricated for life
Clamping hub diameter		mm	48

<sup>a) Application-specific design with cymex® – www.wittenstein-cymex.com
b) For higher ambient temperatures, please reduce input speed
c) At reference ratio and reference speed. Ratio-specific values available in cymex®.</sup>



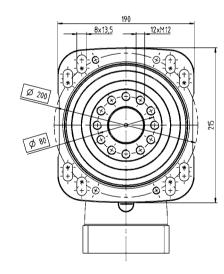


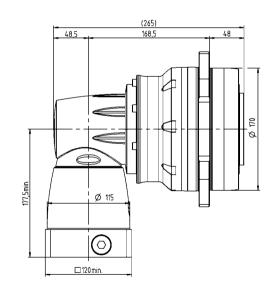


			3-stage
Ratio	i		22 / 27.5 / 38.5 / 44 / 55
Mary Assessed		Nm	1402
Max. torque ^{a)}	T _{2a}	in.lb	12409
Max. acceleration torque	T _{2Not}	Nm	2613
(max. 1000 cycles per hour)	* 2Not	in.lb	23127
Nominal torque	T _{2B}	Nm	950
$(at n_{_{\mathcal{N}}})$, 2B	in.lb	8408
Emergency stop torque	_T	Nm	675
(permitted 1000 times during the service life of the gearbox)	T _{2N}	in.lb	5974
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) ⁽⁵⁾	n _{1T}	rpm	1800 – 2500
Max. input speed	n _{1Max}	rpm	4500
Max. torsional backlash	j_t	arcmin	Standard ≤ 1,3
Torsional rigidity	C	Nm/arcmin	194 – 215
Torsional rigidity	C ₁₂₁	in.lb/arcmin	1717 – 1903
Max. tilting moment	A4	Nm	3600
wax. titting moment	M _{2KMax}	in.lb	31863
Operating noise ©	L _{PA}	dB(A)	≤ 70
Lubrication			Lubricated for life
Clamping hub diameter		mm	28 – 38

<sup>a) Application-specific design with cymex® – www.wittenstein-cymex.com
b) For higher ambient temperatures, please reduce input speed
c) At reference ratio and reference speed. Ratio-specific values available in cymex®.</sup>



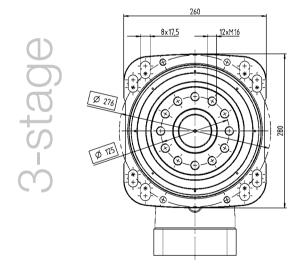


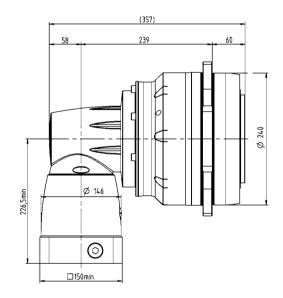


RPC+ 050 MA 3-stage

			3-stage
Ratio	i		22 / 27.5 / 38.5 / 44 / 55
May Agreya (1)	_	Nm	3822
Max. torque ^{a)}	<i>Τ</i> _{2α}	in.lb	33828
Max. acceleration torque	T _{2B}	Nm	3100
(max. 1000 cycles per hour)	2B	in.lb	27437
Nominal torque	T	Nm	1650
(at n _{1N})	T _{2N}	in.lb	14604
Emergency stop torque	7	Nm	5280 – 7150
(permitted 1000 times during the service life of the gearbox)	T _{2Not}	in.lb	46732 – 63283
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) ¹⁹	n _{1T}	rpm	1300 – 1700
Max. input speed	n _{1Max}	rpm	4500
Max. torsional backlash	j_t	arcmin	Standard ≤ 1,3
Torsional rigidity		Nm/arcmin	607 – 671
Torsional rigidity	C _{t21}	in.lb/arcmin	5372 – 5939
Max. tilting moment	Λ.4	Nm	11000
Max. tilting moment	M _{2KMax}	in.lb	97359
Operating noise ^{e)}	L _{PA}	dB(A)	≤ 71
Lubrication			Lubricated for life
Clamping hub diameter		mm	38

<sup>a) Application-specific design with cymex® – www.wittenstein-cymex.com
b) For higher ambient temperatures, please reduce input speed
c) At reference ratio and reference speed. Ratio-specific values available in cymex®.</sup>

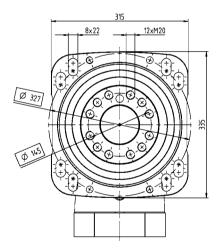


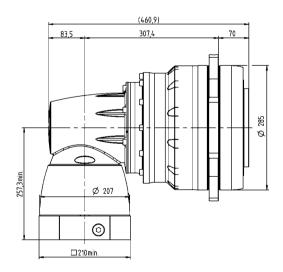


			3-stage
Ratio	i		22 / 27.5 / 38.5 / 44 / 55
Max. torque a	_	Nm	7535
iviax. torque -	T _{2a}	in.lb	66691
Max. acceleration torque	T _{2B}	Nm	5500
(max. 1000 cycles per hour)	2B	in.lb	48679
Nominal torque	T	Nm	3500
(at n,,,)	T _{2N}	in.lb	30978
Emergency stop torque	T	Nm	8580 – 14575
(permitted 1000 times during the service life of the gearbox)	T _{2Not}	in.lb	75940 – 129000
Thermal speed limit (with 20°C ambient temperature and 10% torque utilization) ⁵⁰	n _{1T}	rpm	850 – 1350
Max. input speed	n _{1Max}	rpm	4000
Max. torsional backlash	j_t	arcmin	Standard ≤ 1,8
Torsional rigidity	_	Nm/arcmin	1039 – 1171
Torsional rigidity	C ₁₂₁	in.lb/arcmin	9196 – 10364
Max. tilting moment	14	Nm	21000
wax. titting moment	M _{2KMax}	in.lb	185867
Operating noise ^o	L _{PA}	dB(A)	≤ 71
Lubrication			Lubricated for life
Clamping hub diameter		mm	48

<sup>a) Application-specific design with cymex® – www.wittenstein-cymex.com
b) For higher ambient temperatures, please reduce input speed
c) At reference ratio and reference speed. Ratio-specific values available in cymex®.</sup>







Basic Line gearbox overview



						-	-
Product type		СР	CPS	СРК	CPSK	CVH	cvs
Version		MF	MF	MF	MF	MF / MT	MF/MT
D.: 4	min. <i>i</i> =	3	3	3	3	7	7
Ratio c)	max. <i>i</i> =	100	100	100	100	40	40
Max. torsional backlash	Standard	≤ 12	≤ 12	≤ 13	≤ 15	≤ 15	≤ 15
[arcmin] ^{c)}	Reduced	-	-	-	-	-	-
Output type							
Smooth shaft		х	х	х	х	-	х
Shaft with key d		х	х	х	х	-	х
Splined shaft (DIN 5480)		-	-	-	-	-	-
Blind hollow shaft		-	-	-	-	-	-
Hollow shaft interface		-	-	-	-	х	-
Keyed hollow shaft		-	-	-	-	х	-
Flanged hollow shaft		-	-	-	-	-	-
Flange		-	-	-	-	-	-
System output		-	-	-	-	-	-
Output on both sides		-	-	-	-	х	х
Input type							
Motor-mounted		х	х	х	х	х	х
Self-contained version b)		-	-	-	-	-	-
Characteristic							
Flange with slotted holes		-	-	-	-	-	-
ATEX a)		-	-	-	-	-	-
Food-grade lubrication a) b)		х	х	х	х	х	х
Corrosion resistant a) b)		-	-	-	-	-	-
Optimized mass inertia a)		-	-	-	-	-	-
System solutions							
Linear system (rack/pinion)		-	-	-	-	-	-
Servo actuator		-	-	-	_	-	-
Accessories (please refer to the product pag	es for further o	ptions)					
Coupling		х	х	х	х	-	х
Shrink disc		-	-	-	-	х	-

<sup>a) Power reduction: technical data available on request
b) Please contact WITTENSTEIN alpha
c) In relation to reference sizes
d) Power reduction: Please use our sizing software cymex® for a detailed sizing – www.wittenstein-cymex.com</sup>

Value Line gearbox overview



		-	,		_		-			-		-	-	
Product type		NP	NPL	NPS	NPT	NPR	NPK	NPLK	NPSK	NPTK	NPRK	NVH	NVS	HDV
Version		MF / MA	MF / MA	MF / MA	MF / MA	MF/MA	MF	MF	MF	MF	MF	MF	MF	MF/MT
	min. <i>i</i> =	3	3	3	3	3	3	3	3	3	3	4	4	4
Ratio °	max. <i>i</i> =	100	100	100	100	100	100	100	100	100	100	400	400	400
Max. torsional	Standard	≤ 8	≤ 8	≤ 8	≤ 8	≤ 8	≤ 11	≤ 11	≤ 11	≤ 11	≤ 11	≤ 6	≤ 6	≤ 10
backlash [arcmin] ^{c)}	Reduced	-	-	-	-	-	-	-	-	-	-	-	-	-
Output type								•						
Smooth shaft		×	х	х	-	х	х	х	х	-	х	-	х	х
Shaft with key d)		×	х	х	-	х	х	х	х	-	х	-	х	х
Splined shaft (DIN 5480	D)	-	х	х	-	х	-	х	х	-	х	-	-	-
Blind hollow shaft		-	-	-	-	-	-	-	-	-	-	-	-	-
Hollow shaft interface		-	-	-	-	-	-	-	-	-	-	х	-	-
Keyed hollow shaft		-	-	-	-	-	-	-	-	-	-	х	-	-
Flanged hollow shaft		-	-	-	-	-	-	-	-	-	-	-	-	-
Flange		-	-	-	х	-	-	-	-	х	-	-	-	-
System output		-	-	-	-	-	-	-	-	-	-	-	-	-
Output on both sides		-	-	-	-	-	-	-	-	-	-	х	х	-
Input type														
Motor-mounted		×	х	х	х	х	х	х	х	х	х	х	х	х
Self-contained version	b)	-	-	-	-	-	-	-	-	-	-	-	-	-
Characteristic														
Flange with slotted hole	es	-	-	-	-	х	-	-	-	-	х	-	-	-
ATEX a)		-	-	-	-	-	-	-	-	-	-	-	-	-
Food-grade lubrication	a) b)	×	х	х	х	х	х	х	х	х	х	х	х	х
Corrosion resistant a) b)		-	-	-	-	-	-	-	-	-	-	х	х	х
Optimized mass inertia	a)	-	-	-	-	-	-	-	-	-	-	-	-	-
System solutions														
Linear system (rack/pin	ion)	x	х	х	-	х	х	х	х	-	х	ı	х	-
Servo actuator		-	-	-	-	-	_	-	_	-	_	-	-	х
Accessories (please refer to the produ	uct pages for furt	her options)												
Coupling		х	х	х	-	х	х	х	х	-	х	-	х	-
Shrink disc		-	-	-	-	-	-	-	-	-	-	х	-	-

a) Power reduction: technical data available on request b) Please contact WITTENSTEIN alpha

e In relation to reference sizes
et In relation to reference sizes
et Power reduction: Please use our sizing software cymex* for a detailed sizing – www.wittenstein-cymex.com

Advanced Line gearbox overview

















							13		400
Product type		SP⁺	SP+ HIGH SPEED	SP+ HIGH SPEED friction optimized	TP+	TP+ HIGH TORQUE	HG⁺	SK+	SPK+
Version		MF	MC	MC-L	MF	MA	MF	MF	MF
5)	min. i =	3	3	3	4	22	3	3	12
Ratio c)	max. i =	100	100	10	100	302.5	100	100	10000
Max. torsional backlash	Standard	≤ 3	≤ 4	≤ 4	≤ 3	≤ 1	≤ 4	≤ 4	≤ 4
[arcmin] ^{c)}	Reduced	≤ 1	≤ 2	≤ 2	≤ 1	-	-	-	≤ 2
Output type	,		•			,			
Smooth shaft		х	х	х	_	-	-	х	х
Shaft with key d		х	х	х	-	-	-	х	х
Splined shaft (DIN 5480)		х	х	х	-	-	-	х	х
Blind hollow shaft		х	х	х	-	-	-	-	х
Hollow shaft interface		-	-	-	-	-	х	-	-
Keyed hollow shaft		-	-	-	_	-	-	-	-
Flanged hollow shaft		-	-	-	-	-	-	-	-
Flange		-	-	-	х	х	-	-	-
System output		-	-	-	х	х	-	-	-
Output on both sides		-	-	-	-	-	х	х	х
Input type						,			
Motor-mounted		х	х	х	х	х	х	х	х
Self-contained version b)		х	-	-	х	-	-	-	-
Characteristic									
Flange with slotted holes		х	-	-	_	-	-	-	-
ATEX a)		х	х	-	_	-	х	х	-
Food-grade lubrication a) b)		х	х	х	х	x	х	х	х
Corrosion resistant a) b)		х	х	х	х	х	х	х	х
Optimized mass inertia a)		х	х	х	х	х	-	-	-
System solutions			_						
Linear system (rack/pinion)	х	х	-	х	x	-	х	х
Servo actuator		х	-	-	х	х	-	-	-
Accessories (please refer to the product	pages for further	options)			1				
Coupling		х	х	х	x	х	-	х	х
Shrink disc		х	х	х	_	-	х	-	x

<sup>a) Power reduction: technical data available on request
b) Please contact WITTENSTEIN alpha
c) In relation to reference sizes
d) Power reduction: Please use our sizing software cymex® for a detailed sizing – www.wittenstein-cymex.com</sup>



	-				- MCALIF	and the same of	-	-		
тк∙	TPK+	TPK+ HIGH TORQUE	sc⁺	SPC+	TPC+	VH⁺	VS⁺	VT÷	DP+	HDP+
MF	MF	MA	MF	MF	MF	MF	MF	MF	MF / MA	MA
3	12	66	1	4	4	4	4	4	16	22
100	10000	5500	2	20	20	400	400	400	55	55
≤ 4	≤ 4	≤ 1.3	≤ 4	≤ 4	≤ 4	≤ 3	≤ 3	≤ 3	≤ 3	≤ 1
-	≤ 2	-	_	≤ 2	≤ 2	≤ 2	≤ 2	≤ 2	≤ 1	-
-	-	-	x	x	_	-	х	-	-	-
-	-	-	x	х	_	-	х	-	-	-
-	-	-	-	x	-	-	х	-	-	-
-	-	-	-	x	-	-	-	-	-	-
-	-	-	-	-	-	х	_	-	-	-
-	-	-	-	-	-	х	-	-	-	-
х	-	-	-	-	-	-	-	х	-	-
-	х	х	-	-	х	-	-	-	х	х
-	х	х	-	-	х	-	-	-	-	-
х	x	х	_	-	_	x	x	-	-	-
х	х	х	х	х	х	х	x	х	x	х
-		-	-	-	-	-		-	-	-
-	-	-	_	-	-	-	-	-	-	-
х	-	-	-	-	-	-	_	-	-	-
х	х	х	x	х	x	х	х	х	x	х
х	х	х	-	-	-	х	х	х	х	х
-	-	-	-	-	-	-	_	-	х	х
х	х	х	х	х	х	-	х	х	-	-
-	-	-	-	-	-	-	-	-	-	-
х	х	х	х	х	х	-	x	х	_	-
-	-	-	-	х	-	х	-	-	-	-

Premium Line gearbox overview













			-	200	-		1
Product type		XP⁺	RP⁺	XPK+	RPK⁺	XPC⁺	RPC⁺
Version		MF / MC	MF / MA	MF	MA	MF	MA
Catalog page		24	36	56	60	68	73
D. I. d.	min. i =	3	22	12	48	4	22
Ratio °)	max. i =	100	220	1000	5500	20	55
Max. torsional backlash	Standard	≤ 3	≤ 1	≤ 4	≤ 1.3	≤ 4	≤ 1.3
[arcmin] ⁽⁾	Reduced	≤ 1	-	≤ 2	-	≤ 2	-
Output type			'		'		
Smooth shaft		х	-	х	-	х	-
Shaft with key d		х	-	х	-	х	-
Splined shaft (DIN 5480)		х	-	х	-	х	-
Blind hollow shaft		х	-	х	-	х	-
Hollow shaft interface		-	-	-	-	-	-
Keyed hollow shaft		-	-	-	-	-	-
Flanged hollow shaft		-	-	-	-	-	-
Flange		-	х	-	х	-	х
System output		х	х	х	х	x	х
Output on both sides		-	-	-	-	-	-
Input type			•		•		
Motor-mounted		х	х	х	х	х	х
Self-contained version b)		х	-	-	-	-	-
Characteristic							
Flange with slotted holes		х	х	х	х	х	х
ATEX a)		-	-	-	-	-	-
Food-grade lubrication a) b)		х	х	х	х	х	х
Corrosion resistant a) b)		-	-	-	-	-	-
Optimized mass inertia a)		х	х	-	-	-	-
System solutions							
Linear system (rack/pinion)	х	х	х	х	х	х
Servo actuator		×	х	-	-	-	-
Accessories (please refer to the product p	pages for further o	ptions)					
Coupling		х	_	х	-	x	-
Shrink disc		х	-	х	-	х	-

^{a)} Power reduction: technical data available on request

b) Please contact WITTENSTEIN alpha

<sup>In relation to reference sizes
Power reduction: Please use our sizing software cymex® for a detailed sizing – www.wittenstein-cymex.com</sup>

Servo actuator overview













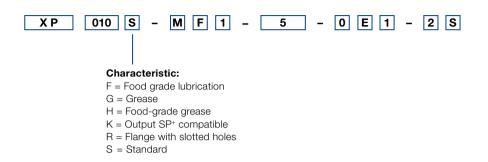


Product type		PBG	PAG	PHG	RPM⁺	TPM+ DYNAMIC	TPM+ HIGH TORQUE	TPM+ POWER
Version		Standard	Standard	Standard	Customer specific	Standard	Standard	Standard
Ratio ©	min. <i>i</i> =	16	16	16	22	16	22	4
natio 5	max. <i>i</i> =	100	100	100	220	91	220	100
Max. torsional backlash c)	Standard	≤ 5	≤ 3	≤ 4	≤ 1	≤ 3	≤ 1	≤3
[arcmin]	Reduced	≤ 3	≤ 1	≤ 2	-	≤ 1	≤ 1	≤ 1
Output shape								
Smooth shaft		х	-	х	_	-	-	-
Shaft with key d)		х	-	х	-	-	-	-
Splined shaft (DIN 5480)		×	-	х	-	-	-	-
Blind hollow shaft		-	-	-	-	-	-	-
Hollow shaft interface		-	-	-	-	-	-	-
Keyed hollow shaft		-	-	-	-	-	-	-
Flanged hollow shaft		-	-	-	_	-	-	-
Flange		-	х	-	x	×	×	х
System output		-	х	х	×	×	×	х
Output on both sides		-	-	-	-	-	-	-
Input type								
Motor-mounted		-	-	-	_	-	-	-
Self-contained version		-	-	-	_	-	-	-
Characteristic								
Flange with slotted holes		-	-	х	x	-	-	-
ATEX a)		-	-	-	-	-	-	-
Food-grade lubrication a) b)		х	х	х	x	х	×	х
Corrosion resistant a) b)		-	-	-	-	х	×	х
Optimized mass Inertia a)		-	-	-	-	-	-	-
System solutions					•			
Linear system (rack / pinion	1)	×	×	х	×	X	×	х
Accessories (please refer to the product p	pages for further o	options)						
Coupling		х	х	-	_	х	×	х
Shrink disc		х	-	x	_	-	-	-
Power cable, signal cable, I	hyprid cable	х	х	х	х	x	x	Х

a) Power reduction: technical data available on request

[|] Power reduction: technical data available on register
| Power reduction: VITTENSTEIN alpha
| In relation to reference sizes
| Power reduction: Please use our sizing software cymex® for a detailed sizing – www.wittenstein-cymex.com

Overview of gearbox variants



Explanation of variants deviating from the standard:

F = Food grade lubrication

These products are available with food-grade lubrication and can therefore be used in the food industry. Please note that the torque ratings in the catalog are reduced by 20 %.

G = Grease

This variant allows you to lubricate selected products with grease instead of oil. Please note that the torque ratings in the catalog are reduced by 20 %.

H = Food-grade grease

This variant allows you to lubricate selected products with food-safe grease instead of oil. Please note that the torque ratings in the catalog are reduced by 40 %.

K = Output SP+ compatible

The XP+ gearboxes are available with an SP+ output compatible housing (square). It is necessary to also choose the SP+ compatible output shaft in order to achieve full output compatibility. The technical data is similar to the SP+. Please contact WITTENSTEIN alpha for detailed information.

R = Flange with slotted holes

This output type is designed for linear applications with rack and pinion or belt pulley. Integrated slotted holes enable easy positioning of the pinion or simple tensioning of the belt.

R-flange with slots for XP+, XPK+ and XPC+ gearboxes

The R-flange has become indispensable in rack and pinion drive trains: it is the benchmark for modularity and ease of installation. That's why the R-flange is also used in our XP+ family as both a coaxial and a right-angle version, with a host of design options.

Benefits compared to the standard version:

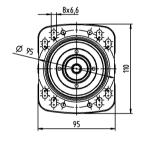
- Easy mounting and positioning of the gearbox with a mounted pinion in relation to the rack
- · Lower design costs
- · Potential saving because no additional design elements are needed, e.g. intermediate plates
- · More design freedom due to higher compactness

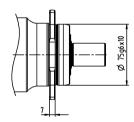


Premium Linear Systems with XP+ R

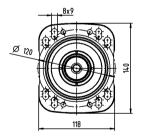
Views

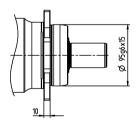
XP+ 020 R



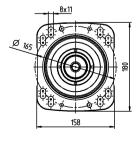


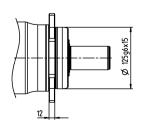
XP+ 030 R





XP+ 040 R





Special assembly washers for the slotted version are included in the scope of delivery.

alpha Premium Linear Systems

A new dimension in performance

With the Premium Linear System, the performance of the rack and pinion system enters a new dimension. While others are still busy adapting existing solutions, WITTENSTEIN alpha has stayed several steps ahead by developing the new linear systems. The innovative Premium Linear System is used in all applications where the individual requirements far exceed what has previously been possible. Compared to the industry standard, the values have been improved by 150 % on average.

The alpha preferential linear system – The best from each segment

Our preferential linear systems in the premium segment are always comprised of the perfect combination of gearbox, pinion, rack and lubrication system. The systems have been optimized to achieve the required feed force, feed speed, stiffness and degree of utilization of the individual components.



For further information, refer to our alpha Linear Systems catalog and our website:

www.wittenstein-alpha. com/linear-systems

For a wide range of applications

Linear systems from WITTENSTEIN alpha are suitable for a wide range of applications and industries. New standards and advantages have been achieved in the following areas:

- · Smooth operation
- · Positioning accuracy
- · Feed force
- · Power density
- Rigidity
- · Easy installation
- · Design options
- · Scalability

Together with a comprehensive range of services, we pledge to support you from the initial concept to the design, installation and commissioning phase. We will also ensure a consistent supply of spare parts.

Your benefits at a glance

Perfectly matched components

Maximum efficiency and power density

Exceptional linear system rigidity for even greater dynamics and precision

Simple mounting and maximum integration in the drive train

Available in different sizes, power categories and segments

Consultation and quality – everything from a single





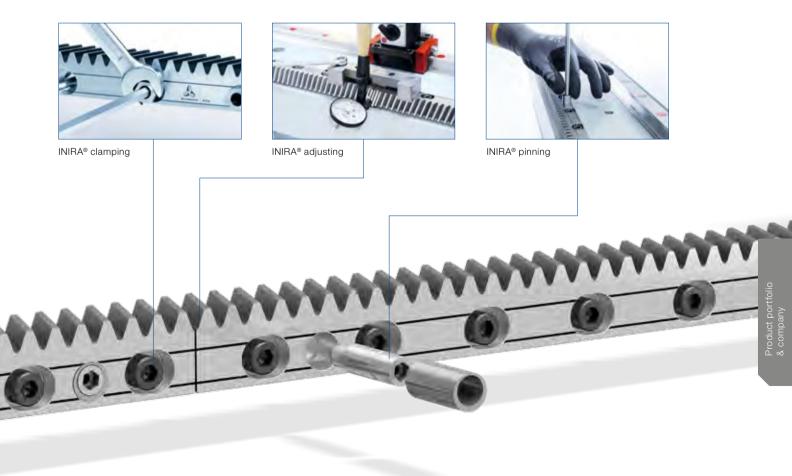
Simply scan the QR code using your smartphone to see INIRA® in action.

INIRA® combines our existing innovative concepts for the simple, safe and efficient installation of racks. INIRA® clamping, INIRA® adjusting and INIRA® pinning have already made the assembly process much faster, more accurate and more ergonomic. Available for the Advanced and Premium Linear Systems.

INIRA® clamping: Simply faster and more ergonomic Previously, enormous effort was required to clamp racks to the machine bed using screw clamps. INIRA® clamping integrates the clamping device in the rack. The rack incorporates a mounting sleeve which is guided over the head of the fastening screw to ensure quick and ergonomic clamping.

INIRA® pinning: Simply better and more efficient The previous method used for pinning racks was extremely time-consuming. Precision bores have to be drilled and the chips generated must be carefully removed from the assembly. INIRA® pinning now offers a completely new solution for the chipless pinning of racks, which reduces installation times considerably (time spent on each rack ~ 1 min).

INIRA® adjusting: Simply safer and more precise In combination with INIRA® clamping, INIRA® adjusting is the ideal solution for perfectly adjusting the transition between two rack segments. The innovative setting tool can adjust the transition extremely reliably and precisely, accurate to the micrometer.



Precision meets motion = premo® by WITTENSTEIN alpha

premo® is a powerful servo actuator platform that combines absolute precision with perfect movement. The central idea behind this first fully scalable servo actuator platform is uncompromising flexibility from the viewpoint of the user. Motors and gearboxes with application-related graduated performance characteristics can be configured modularly to individual servo actuators. The result is a

highly versatile modular system with customizable power, designed for a wide variety of applications. The core of the servo actuator is a torsionally rigid precision gearbox with low backlash and excellent torque density combined with the equally powerful, permanent magnet servo motor with a split winding that guarantees low cogging and minimal velocity ripple.

premo® - clearly superior in performance

- · Higher machine performance thanks to higher acceleration torque
- · High torque density combined with a compact design allow for the realization of higher performance machines with significant space saving
- · Improved connectivity to next generation controllers from leading system providers through the use of digital feedback (EnDat 2.2, DSL, HIPERFACE DSL®, DRIVE-CLiQ)
- · Compatibility for high bus voltages up to 750 V DC
- · Reduced wiring requirement through single-connector technology
- · Improved reliability and safety through the use of more powerful brakes and SIL 2 encoders



premo® SP Line

Product highlights

Optimized power density for greater energy efficiency and productivity

Flexible mechanical and electrical interfaces for high scalability

Variety of options for individually upgrading the basic configuration



- premo® TP Line, size 3
- TPM+ 025

premo® application examples



Handling portal premo® SP Line



Fill and Seal machine premo® TP Line



Milling cutter for a machining center premo® XP Line

Typical fields of application and industry solutions

- · Delta robot (axes 1-3, swivel axis)
- · Handling portal (Z-axis, swivel/rotating axis)
- · Machine tool reaming (rotating axes A-C, tool changer)
- · Fill and Seal Machine (incl. jaw stroke, sealing jaw, blade)
- · Folding carton packaging (incl. assembly / folding, filling valve)
- · Plastic thermoform (tool axis)



Galaxie® drive system - Performance in a new dimension







Next Technology Drive

This award-winning innovation by WITTENSTEIN surpasses all previous drives in terms of torsional backlash, torque density, stiffness and compactness. The innovative core of the Galaxie® is that the drive makes almost full surface contact during power transmission, which produces a defined torque density as well as exceptional torsional rigidity and zero backlash – even at the zero crossing.

Product highlights

Our advantage and your benefit:

High torsional rigidity

No backlash - even at the zero crossing

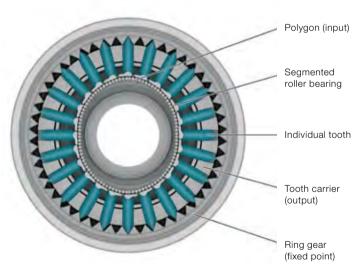
Hydrodynamic surface contact

Maximum torque density

High robustness

Hollow shaft

Schematic diagram

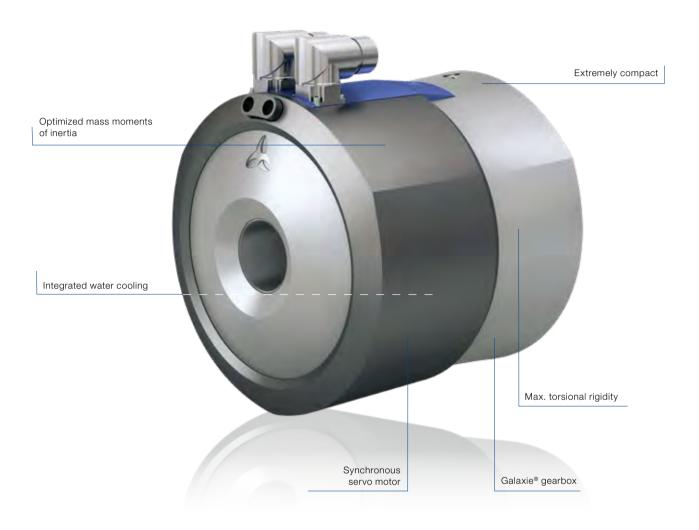


Complete system under one roof Options:

- · Integrated holding brake
- · Different feedback systems
- · Additional encoder system at the input



Find out more about the Galaxie® by simply scanning the QR code using your smartphone.





Galaxie® mounted on a milling cutter manufactured by Maka Systems GmbH for processing carbon composite materials – High Speed for maximum component quality



Galaxie $^{\rm @}$ in a spline rolling machine – faster processing speeds increase productivity by 40 %

Accessories – smart additions for intelligent performance

Gearboxes, accessories and consulting from a single source

WITTENSTEIN alpha drive solutions: Perfectly matched From a single source Overall responsibility Consultation

Optimization of your added value chain

Use the combination of gearbox and accessories in a complete package to streamline your internal processes.

Gearbox process costs	Accessory process costs
Two suppliers	
100 %	100 %
Complete delivery by WITTE	NSTEIN alpha
	Up to 80 %

Shrink disks

Shrink disks are frictional hub / shaft connections. Together with our hollow shaft or mounted shaft gearboxes for mounting directly on load shafts, machines can be designed to take up a minimal installation space.

The benefits:

- · Simple mounting and removal
- · Quick selection, easy and convenient
- · Optional: corrosion resistant version



Preferred shrink disk series

To view a wide range of nickel-plated, stainless steel and other shrink disks as well as all the relevant technical data and dimensions, visit our homepage

www.wittenstein-alpha.com

Couplings

Couplings are used for compensating misalignment during assembly and material-related heat expansion

Compensation for shaft misalignment











Metal bellows coupling

- · Compensation for shaft misalignment
- · Completely backlash free
- · Corrosion resistant version available as an option (BC2, BC3, BCT)
- · High torsional rigidity



Elastomer coupling

- · Compensation for shaft misalignment
- · Completely backlash free
- · Selectable torsional rigidity/damping
- · Compact design
- · Extremely simple installation (plug-in)



Torque limiter

- · Compensation for shaft misalignment
- · Completely backlash free
- · Precise, preset overload protection (switch-off in 1 - 3 ms)
- · Precise repeat accuracy
- · Just one protection element per axis

Preferred coupling series







Preferred series are defined for the relevant gearbox segments to make selection easier. Preferred couplings are defined based on the maximum torque that the gearbox can transmit. Standard industrial conditions for the number of cycles (1000/h) and ambient temperature were adopted.

Please note that the coupling load is based on the torque that the gearbox can transmit and not the torque in your application. We recommend using our cymex®5 design software to create a more detailed design. (www.wittenstein-cymex.com)

For more coupling types, please visit www.wittenstein-alpha.com

Support at each interaction stage

With the WITTENSTEIN alpha service concept, we are also setting new standards in the field of customer support.

Global presence

Our global consultation network will help you overcome your complex challenges through our extensive experience, a variety of design tools and individual engineering services.

Speed counts

Our speedline® team guarantees fast response times in the area of logistics. We provide on-site support during the installation and commissioning of mechanical systems to give you a sustained competitive edge.

Personal consultation

Our highly qualified and committed expert personnel will accompany you throughout the entire product lifecycle - around the clock. When it comes to customer support, you can count on us!

Design

Consultation
CAD POINT
SIZING ASSISTANT
Sizing software cymex®
Engineering

Installation

speedline® delivery Installation on-site Operating & installation instructions Pick-up & return service



We are happy to advise you:

24 h service hotline:

+49 7931 493-12900

No matter where you need us:

A comprehensive sales and service network provides quick availability and competent support worldwide.



Maintenance

24 h service hotline Maintenance and inspection Repair cymex® statistics Modernization

Training

Product training Sizing training Installation training Service training

Support at each interaction stage

Design

Whatever your requirements are: we offer the right design methodology. Use the CAD POINT to gain easy access to CAD files, the SIZING ASSISTANT for creating simple

designs, cymex® 5 for precise dimensioning and our engineering service for individual solutions.

Consultation

- · Personal contact on-site
- · Professional application calculations and drive design create the best solutions

Engineering

Catalog gearboxes:

- · Advanced software tools for accurate calculation, simulation and analysis of the drive train
- Optimization of your productivity and reduction in development costs

Special gearboxes:

- · Gearing design and development
- · Development and production of special gearboxes
- \cdot Send all inquiries to: ${\bf sondergetriebe@wittenstein.de}$



CAD POINT

- · 3D data of selected solution
- · Online comparison with motor geometry
- Transparent and simple selection of required components



SIZING ASSISTANT

- · Efficient online design within seconds
- · Convenient comparison function
- · Automatic geometry adjustment



cymex® 5 sizing software

- · Dimensioning, design and evaluation of the entire drive train
- · Reliable, efficient design
- · Optimization of drive system



Installation

All delivered products are perfectly matched to your application environment and fully operational right away.

Our service experts support you in the installation and commissioning of complex mechatronic systems, guaranteeing maximum availability of your plant.

speedline® delivery

Tel. +49 7931 493-10444

- · Delivery of standard series in 24 or 48 hours ex works*
- · Outstanding flexibility for fast deliveries at short notice

Installation on-site

- · Professional installation
- · Optimal integration of the system in your application
- · Explanation of the drive function

Operating and installation instructions

- · Detailed explanations of how to use the product
- · Motor installation videos
- · Assembly videos on rack and pinion system

Pick-up and return service

- · Cost savings through minimization of downtimes
- · Professional logistics organization
- · Reduction of transport risks through customized, direct pick-up and delivery



^{*} Non-binding delivery time depending on part availability.

Support at each interaction stage

Maintenance

WITTENSTEIN alpha guarantees fast repairs of the highest quality and precision – with short throughput times and intensive support. In addition, we will provide you with information about various measurements, material

analyses and condition monitoring inspections. You can rely on short response times, unbureaucratic processing and individual support.

24 h service hotline

Tel. +49 7931 493-12900

- · Available round the clock
- Personal, prompt service for resolving time-critical maintenance issues

Maintenance and inspection

- Documentation regarding condition and expected service life
- · Maintaining required state
- · Customized maintenance schedules

Repair

- · Restoring to required state
- · Short throughput times
- \cdot Immediate response in time-critical situations

cymex® statistics

- · Systematic field data acquisition
- · Reliability calculations (MTBF)
- · Customized evaluations

Modernization

- · Professional retrofitting
- · Reliable compatibility testing of existing solutions



Training

Discover how our products function and how they can add value to your application. We offer you training courses at our premises or on-site at your plant. Benefit from

practice-oriented learning methods and a highly skilled team of trainers.

Product training

Greater knowledge enables greater achievement. We will be pleased to share our expert knowledge with you: Profit from our many years of experience and learn more about the product portfolio of WITTENSTEIN alpha.

Sizing training

Become a design expert! We will provide you with training courses on our design software, adapted to your requirements. Whether for beginners or experts, for occasional or regular users – we adapt our training course to your wishes and requirements.

Installation training

We offer you individual training courses on-site for your system application of selected linear axes as well as professional installation.

Service training

Participation in a service training course is a prerequisite for sourcing spare parts at the parts list level. We offer you training courses at our premises or on-site at your plant. Moreover, we regularly host maintenance workshops at which the participants are instructed in safe handling during mounting of the motor to the gearbox as well as the independent replacement of wearing parts and gearbox assemblies.



The WITTENSTEIN group – The company and its fields of business



With approximately 2,900 employees worldwide, WITTENSTEIN SE stands for innovation, precision and excellence in the world of mechatronic drive technology, both nationally and internationally. The group is active in six innovative fields of business. Furthermore, WITTENSTEIN SE is represented by some 60 subsidiaries in around 40 countries in all important technology and sales markets worldwide.



Our fields of expertise

We provide know-how for a host of different sectors:

- · Machine and plant construction
- · Software development
- · Aerospace
- · Automotive & E-mobility
- · Energy
- · Oil & Gas Exploration and Production
- $\cdot \ \text{Medical technology}$
- · Measurement and testing technology
- · Nanotechnology
- · Simulation

The WITTENSTEIN Group



alpha

WITTENSTEIN alpha GmbH High-precision servo drives and linear systems





cyber motor

WITTENSTEIN cyber motor GmbH Highly dynamic servo motors and drive electronics





galaxie

WITTENSTEIN galaxie GmbH Superior gearboxes and drive systems





motion control

WITTENSTEIN motion control GmbH Customized linear and rotary servo systems





aerospace & simulation

WITTENSTEIN aerospace & simulation GmbH Mechatronic drive systems for aerospace & simulation





attocube systems AG Nanoprecision drive and measurement technology solutions





baramundi software AG Secure management of IT infrastructure in offices and production areas



alpha Premium Line - Gearbox design

We recommend using cymex® 5 sizing software to dimension the complete drive train in detail.



cymex®5

- Calculate on the Best
- Detailed calculation of complete drive trains
- Precise simulation of motion and load variables
- Downloadable software for complex designs

www.wittenstein-cymex.com



Operating mode:

In order to assess the application in detail. a distinction must be made between two operating modes.

1. Cyclic operation S5:

- · Number of cycles ≤ 1000/hour
- · Duty cycle < 60 % and < 20 minutes

Recommended gearbox model: MF/MA version

2. Continuous operation S1:

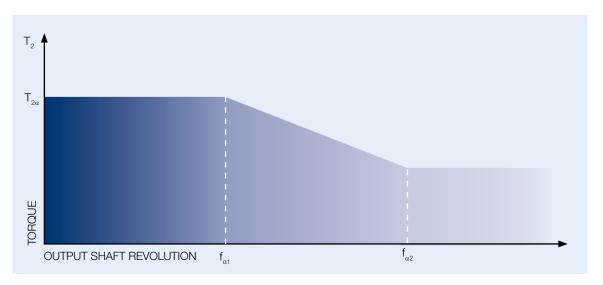
· Duty cycle ≥ 60 % or ≥ 20 minutes

Recommended gearbox model: MC version

Max. torque $T_{2\alpha}$:

 $T_{2\alpha}$ represents the maximum torque transmitted by the gearbox. Once the number of cycles and the shock factor have been determined, the maximum acceleration torque can be calculated at the output $(T_{2b, fs})$. The maximum torque $T_{2\alpha}$ must be reduced in line with the relevant output shaft revolutions (f_{α}) .

The calculated torque $T_{2b, fs}$ must not exceed the maximum torque T_{2a} of the gearboxes.



Torque in line with the relevant output shaft revolution

Max. tilting torque M_{2kmax}:

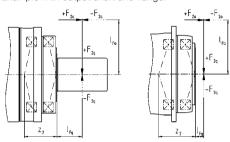
The maximum tilting moment $\mathbf{M}_{\mathrm{2kmax}}$ can be calculated using the following formula:

$$M_{2kmax} = \frac{F_{2aMax} \cdot I_{Fa} + F_{2qMax} \cdot (I_{Fq} + Z_2)^{a)}}{W^{b)}}$$

$$a) I_{Fa', Fq}, Z_2 \text{ in mm}$$

$$b) W = 1000 \text{ (metric)}$$

Example with output shaft and flange:



One prerequisite of the calculation is that the axial force is applied centrally and does not exceed 37 % in relation to the radial force.

XP⁺		010	020	030	040	050
_	[mm]	75.3	91.5	115	101.2	128.4
Z_2	[in]	2.96	3.60	4.53	3.98	5.06

RP⁺		030	040	050	060	080
_	[mm]	93.5	106.1	141.9	181.9	195.6
Z ₂	[in]	3.68	4.18	5.59	7.16	7.70

Drive options:



Clamping hub with socket (standard)



Optimized mass inertia clamping hub – For highly dynamic applications



Clamping hub with keyed socket – the form fit connection for even the highest safety requirements

Glossary – the alphabet

Adapter plate

WITTENSTEIN alpha uses a system of standardized adapter plates to connect the motor and the gearbox, making it possible to mount a WITTENSTEIN alpha gearbox to any desired motor without difficulty.

Angular minute

A degree is subdivided into 60 angular minutes (= 60 arcmin = 60').

Example:

If the torsional backlash is $j_{\rm t}=1$ arcmin, the output can be turned 1/60°. The repercussions for the application are determined by the arc length:

 $b = 2 \cdot \pi \cdot r \cdot \alpha^{\circ} / 360^{\circ}$.

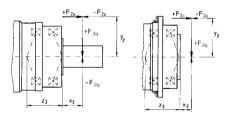
Example:

A pinion with a radius r = 50 mm mounted on a gearbox with torsional backlash $j_t = 3$ arcmin can be turned b = 0.04 mm.

Axial force (F_{2AMax})

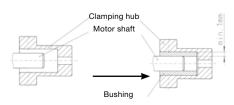
The axial force acting on a gearbox runs parallel to its output shaft or perpendicular to its output shaft. It may be applied with axial offset via a lever arm y_2 under certain circumstances, in which case it also generates a bending moment. If the axial force exceeds the permissible catalog values (max. axial force $F_{\rm 2AMax}$), additional design features (e.g. axial bearings) must be implemented to absorb these forces.

Example with output shaft and flange:



Bushing

If the motor shaft diameter is smaller than the \rightarrow clamping hub, a bushing is used to compensate the difference in diameter. The bushing must have a minimum thickness of 1 mm and a motor shaft diameter of 2 mm.



CAD POINT

Performance data, dimension sheets and CAD data for all types of gearbox can be found online in our CAD POINT together with comprehensive documentation of the selection.

(www.wittenstein-cad-point.com)

Clamping hub

The clamping hub ensures a frictional connection between the motor shaft and gearbox. A \rightarrow bushing is used as the connecting element if the motor shaft diameter is smaller than that of the clamping hub. Optionally, a positive connection via a parallel key is also possible.

Continuous operation (S1)

Continuous operation is defined by the → duty cycle. If the duty cycle is greater than 60% and / or longer than 20 minutes, this qualifies as continuous operation. → Operating modes

Cyclic operation (S5)

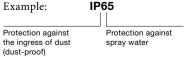
Cyclic operation is defined via the \rightarrow duty cycle. If the duty cycle is less than 60% and shorter than 20 minutes, it qualifies as cyclic operation (\rightarrow operating modes).

cymex®

cymex® is the calculation software developed by our company for dimensioning complete drive trains. The software enables the precise simulation of motion and load variables. The software is available for download from our website (www.wittenstein-cymex. com). We can also provide training to enable you to make full use of all the possibilities provided by the software.

Degree of protection (IP)

The various degrees of protection are defined in DIN EN 60529 "Degrees of protection offered by enclosure (IP code)". The IP degree of protection (International Protection) is represented by two digits. The first digit indicates the protection against the ingress of impurities and the second the protection against the ingress of water.



Duty cycle (DC)

The cycle determines the duty cycle DC. The times for acceleration $(t_{\rm b})$, constant travel if applicable $(t_{\rm c})$ and deceleration $(t_{\rm o})$ combined yield the duty cycle in minutes. The duty cycle is expressed as a percentage with inclusion of the pause time t.

DC [min] = $t_{p} + t_{q} + t_{d}$

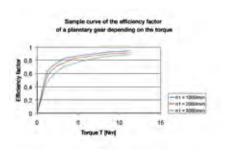
Emergency stop torque (T_{2Not})

The Emergency stop torque $T_{\rm 2Not}$ is the maximum permissible torque at the gearbox output and must not be reached more than 1000 times during the life of the gearbox. It must never be exceeded!

Efficiency (η)

Efficiency [%] η is the ratio of output power to input power. Power lost through friction reduces efficiency to less than 1 or 100%.

$$\eta = P_{\text{off}}/P_{\text{on}} = (P_{\text{on}} - P_{\text{loss}})/P_{\text{on}}$$



WITTENSTEIN alpha always measures the efficiency of a gearbox during operation at full load. If the input power or torque are lower, the efficiency rating is also lower due to the constant no-load torque. Power losses do not increase as a result. A lower efficiency is also expected at high speeds (see illustration).

Ex symbol



Devices bearing the Ex symbol comply with EU Directive 94 / 9 / EC (ATEX) and are approved for use in defined explosion-hazardous zones.

Detailed information on explosion groups and categories, as well as further information on the relevant gearbox are available upon request.

HIGH SPEED (MC)

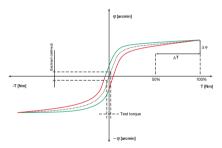
The HIGH SPEED version of our gearbox has been specially developed for applications in continuous operation at high input speeds, e.g. as found in the printing and packaging industries.

HIGH TORQUE (MA)

WITTENSTEIN alpha gearboxes are also available in a HIGH TORQUE version. These gearboxes are particularly suited to applications requiring extremely high torques and maximum stiffness.

Hysteresis curve

The hysteresis is measured to determine the torsional rigidity of a gearbox. The result of this measurement is known as the hysteresis curve.



If the input shaft is locked, the gearbox is continuously loaded and relieved at the output in both directions up to a defined torque. The torsional angle is plotted against the torque. This yields a closed curve from which the → torsional backlash and → torsional rigidity can be calculated.

Jerk (i)

Jerk is derived from acceleration and is defined as the change in acceleration within a unit of time. The term impact is used if the acceleration curve changes abruptly and the jerk is infinitely large.

Lateral force (F_{2QMax})

The max. lateral force F_{2OMax} [N] is the force component acting at right angles to the output shaft or parallel to the output flange. It acts perpendicular to the \rightarrow axial force and can assume an axial distance of x_2 in relation to the shaft nut or shaft flange, which acts as a lever arm. The lateral force produces a bending moment (see also \rightarrow axial force).

Mass inertia ratio (λ = Lambda)

The mass inertia ratio λ is the ratio of external inertia (application side) to internal inertia (motor and gearbox side). It is an important parameter determining the controllability of an application. Accurate control of dynamic processes becomes more difficult with differing mass moments of inertia and as λ becomes greater. WITTENSTEIN alpha recommends that a guideline value of $\lambda < 5$ is maintained. A gearbox reduces the external mass moment of inertia by a factor of $1/i^2$.

$$\lambda = \frac{J_{\text{extern}}}{J_{\text{intern}}}$$

J reduced externally at input:

$$J'_{\text{external}} = J_{\text{external}} / i^2$$

Simple applications \leq 10 Dynamic applications \leq 5 Highly dynamic applications \leq 1

Mass moment of inertia (J)

The mass moment of inertia *J* [kg/cm²] is a measurement of the effort applied by an object to maintain its momentary condition (at rest or moving).

Mesh frequency (f_.)

The mesh frequency may cause problems regarding vibrations in an application. especially if the excitation frequency corresponds to a intrinsic frequency of the application. The mesh frequency can be calculated for planetary gearboxes from WITTENSTEIN alpha (exception: gearboxes with ratio i = 8) using the formula $f_7 = 1.8 \cdot n_9$ [rpm] and on planetary gearboxes from WITTENSTEIN alpha, is independent of the ratio. If it does indeed become problematic, the intrinsic frequency of the system can be changed or another gearbox (e.g. hypoid gearbox) with a different mesh frequency can be selected.

No-load running torque (T_{012})

The no-load running torque T_{012} is the torque which must be applied to a gearbox in order to overcome the internal friction; it is therefore considered lost torque. The values specified in the catalog are calculated by WITTENSTEIN alpha at a speed of $n_1 = 3000$ rpm and an ambient temperature of 20 °C.

$$T_{012}$$
: 0 1 \rightarrow 2 without from input side towards output side

Idling torques decrease during operation.

NSF

Lubricants certified as grade H1 by the NSF (National Sanitation Foundation) can be used in the food sector where occasional unavoidable contact with food cannot be excluded.

Operating modes

(continuous operation **S1** and cyclic operation **S5**)

Gearboxes are selected depending on whether the motion profile is characterized by frequent acceleration and deceleration phases in \rightarrow cyclic operation (S5) as well as pauses, or whether it is designed for \rightarrow continuous operation (S1), i.e. with long phases of constant motion.

Operating noise (L_{PA})

The gear ratio and speed affect the noise level. As a general rule: A higher speed means a higher noise level, while a higher ratio means a lower noise level. The values specified in our catalog are based on a reference ratio and speed. The reference speed is either n1= 3000 rpm or n1= 2000 rpm depending on the size of the gearbox. You can find ratio-specific values in cymex® – www.wittenstein-cymex.com.

Output shaft revolution (f)

Factor f_{α} determines the number of life time cycles for the required gearbox service life. It describes the number of revolutions at the output used to assess the torque permitted at the output.

Glossary – the alphabet

Positioning accuracy

The positioning accuracy is determined by the angular deviation from a setpoint and equals the sum of the torsional angles due to load →(torsional rigidity and torsional backlash) and kinetics→(synchronization error) occurring simultaneously in practise.

Quality control

All Premium and Advanced gearboxes are subject to a final inspection before they leave the WITTENSTEIN alpha factory to ensure that they are all delivered within specification.

Ratio (i)

The gear ratio i indicates the factor by which the gearbox transforms the three relevant parameters of motion (speed, torque and mass moment of inertia). The factor is a result of the geometry of the gearing elements (Example: i = 10).

Safety note

For applications with special safety requirements (e.g. vertical axes, clamped drives), we recommend exclusive use of our Premium and Advanced products (excluding V-Drive).

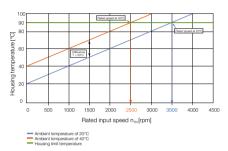
SIZING ASSISTANT

The online SIZING ASSISTANT from WITTENSTEIN alpha allows the efficient selection of a gearbox in seconds. You can use various motor or application entry options to select the right gearbox for your application in seconds (www.sizing-assistant.com).

Speed (n)

Two speeds are of relevance when dimensioning a gearbox: the maximum speed and the thermal speed limit at the input. The maximum permissible speed $n_{\scriptscriptstyle 1 \text{Max}}$ must not be exceeded because it serves as the basis for dimensioning \rightarrow cyclic operation. The nominal speed $n_{\scriptscriptstyle 1 \text{N}}$ must not be exceeded in \rightarrow continuous operation. The thermal speed limit $n_{\scriptscriptstyle 1 \text{T}}$ at an ambient temperature of 20° C, is determined by the maximum

gearbox temperature of $T=90^{\circ}$ C at no-load. As can be seen in the diagram below, the temperature limit is reached more quickly in the presence of an elevated outside temperature. In other words: the nominal input speed must be reduced if the ambient temperature is high.



Delivery of speedline®

If necessary, you can receive delivery of standard series in 24 or 48 hours ex works. Outstanding flexibility for fast deliveries at short notice

Synchronization

Synchronization refers to the measurable speed variation between the input and output during one revolution of the output shaft. It is caused by manufacturing tolerances and causes minute angular deviations and ratio fluctuations.

Technical data

You can download further technical data relating to the entire product portfolio from our website

Tilting rigidity

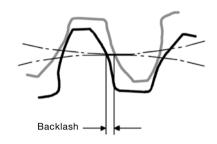
The tilting rigidity $C_{\rm 2K}$ [Nm/arcmin] of the gearbox consists of the bending stiffness of the output or pinion shaft and the stiffness of the output bearing. It is defined as the quotient of tilting moment $M_{\rm 2K}$ [Nm] and tilting angle Φ [arcmin] $(C_{\rm 2K} = M_{\rm 2K}/\Phi)$.

Tilting torque (M_{2K})

The tilting torque $M_{\rm 2K}$ is a result of the ightharpoonup and lateral forces applied and their respective points of application in relation to the inner radial bearing on the output side.

Torsional backlash (j,)

Torsional backlash $j_{\rm t}$ [arcmin] is the maximum angle of torsion of the output shaft in relation to the input. Simply put, the torsional backlash represents the gap between two tooth flanks.



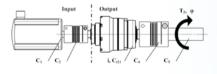
Torsional backlash is measured with the input shaft locked

The output is then loaded with a defined test torque in order to overcome the internal gearbox friction. The main factor affecting torsional backlash is the face clearance between the gear teeth. The low torsional backlash of WITTENSTEIN alpha gearboxes is due to their high manufacturing accuracy and the specific combination of gear wheels.

Torsional rigidity (C₁₂₁)

Torsional rigidity [Nm/arcmin] C_{t21} is defined as the quotient of applied torque and resulting torsion angle $(C_{t21} = \Delta T/\Delta \phi)$. It shows the torque required to turn the output shaft by one angular minute. The torsional rigidity can be determined from the \rightarrow hysteresis curve.

Torsional rigidity C, angle of torsion ϕ



Reduce all torsional rigidity values at the output:

$$C_{\text{(n),out}} = C_{\text{(n),in}} * i^2$$

with i = Gearbox ratio [-] $C_{\text{(n)}} = \text{Individual rigidity values } [\text{Nm/arcmin}]$

Note: The torsional rigidity $C_{\rm t21}$ for the gearbox always relates to the output.

Series connection of torsional rigidity values

$$1/C_{\text{tot}} = 1/C_{1,\text{out}} + 1/C_{2,\text{out}} + ... + 1/C_{(n)}$$

Angle of torsion ϕ [arcmin]

$$\Phi$$
 = T_2 * 1/ C_{tot}
with T_2 = output torque [Nm]

Torque (M)

The torque is the actual driving force of a rotary motion. The force and lever arm combine to produce the torque that acts around the axis of rotation. $M = F \cdot I$

Torque ($T_{2\alpha}$) $T_{2\alpha}$ represents the maximum torque transmitted by the gearbox. This value may decrease depending on the applicationspecific conditions and the precise evaluation of the movement profile.



Glossary – Formulae

Formulae

Torque [Nm]	$T = J \cdot \alpha$	$J = \text{Mass moment of inertia [kgm}^2]$ $\alpha = \text{Angular acceleration [1/s}^2]$	
Torque [Nm]	T=F·I	F = Force [N] I = Lever, length [m]	
Acceleration force [N]	$F_b = m \cdot a$	m = Mass [kg] a = Linear acceleration [m/s²]	
Frictional force [N]	$F_{\text{Reib}} = m \cdot g \cdot \mu$	g = Acceleration due to gravity 9.81 m/s ² μ = Coefficient of friction	
Angular speed [1/s]	$\omega = 2 \cdot \pi \cdot n / 60$	n = Speed [rpm] $\pi = \text{PI} = 3.14$	
Linear speed [m/s]	$V = \omega \cdot r$	r = Radius [m]	
Linear speed [m/s] (spindle)	$V_{\rm sp} = \omega \cdot h / (2 \cdot \pi)$	h = Screw pitch [m]	
Linear acceleration [m/s²]	$a = v/t_b$	$t_{\rm b}$ = Acceleration time [s]	
Angular acceleration [1/s²]	$\alpha = \omega / t_{\rm b}$		
Pinion path [mm]	$s = m_{n} \cdot z \cdot \pi / \cos \beta$	$m_{_{\rm n}} = {\rm Normal\ module\ [mm]}$ $z = {\rm Number\ of\ teeth\ [-]}$ $\beta = {\rm Helix\ angle\ [^{\circ}]}$	

Conversion table

1 mm	= 0.039 in	
1 Nm	= 8.85 in.lb	
1 kgcm²	= 8.85 x 10 ⁻⁴ in.lb.s ²	
1 N	= 0.225 lb _f	
1 kg	= 2.21 lb _m	

Symbol

Symbol	Unit	Designation
С	Nm/arcmin	Stiffness
ED	%, min	Duty cycle
F	N	Force
$f_{_{\mathrm{S}}}$	-	Load factor
$f_{\rm e}$	_	Factor for duty cycle
i	-	Ratio
j	arcmin	Backlash
J	kgm²	Mass moment of inertia
K1	Nm	Factor for bearing calculation
L	h	Service life
L _{PA}	dB(A)	Operating noise
m	kg	Mass
М	Nm	Torque
n	rpm	Speed
p	_	Exponent for bearing calculation
η	%	Efficiency
t	S	Time
Т	Nm	Torque
V	m/min	Linear speed
Z	1/h	Number of cycles

Index

Index	Designation		
Capital letter	Permissible values		
Small letter	Actual values		
1	Input		
2	Output		
A/a	Axial		
B/b	Acceleration		
С	Constant		
d	Deceleration		
е	Pause		
h	Hours		
K/k	Tilting		
m	Mean		
Max/max	Maximum		
Mot	Motor		
N	Nominal		
Not/not	Emergency stop		
0	No load		
Q/q	Lateral		
t	Torsional		
Т	Tangential		

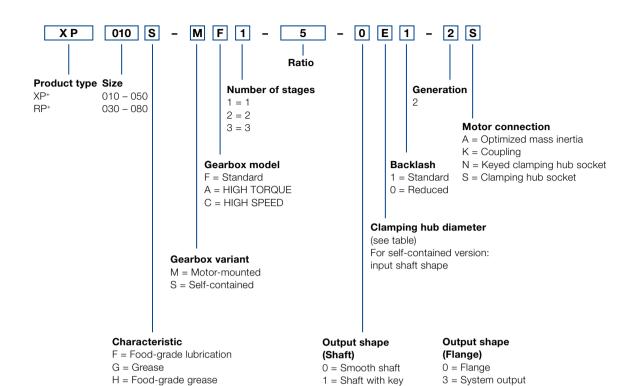
XP+/RP+ - Ordering code

K = Output compatible with SP+

R = Flange with slotted holes

W = Corrosion resistant

S = Standard





2 = Splined shaft

(DIN 5480)

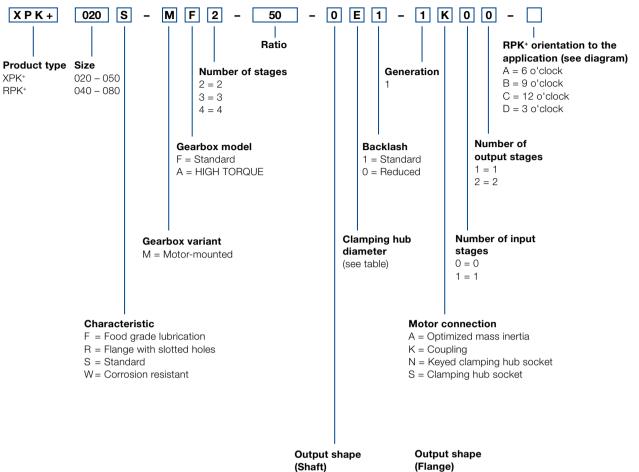
3 = System output

5 = Blind hollow shaft

4 = Other

4 = Other

XPK+/RPK+ - Ordering code

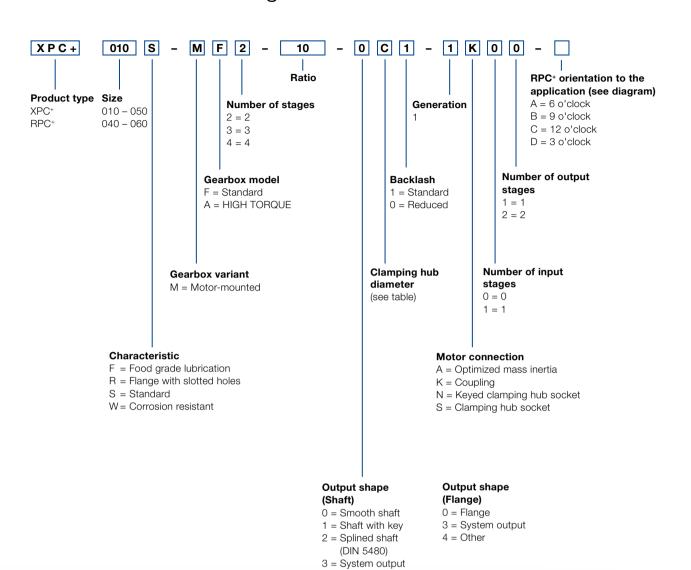


(Shaft)

- 0 = Smooth shaft
- 1 = Shaft with key
- 2 = Splined shaft (DIN 5480)
- 3 = System output
- 4 = Other
- 0 = Flange
- 3 = System output
- 4 = Other



XPC+/RPC+ - Ordering code





Mounting positions and clamping hub diameters

Planetary gearboxes

B5 V1 V3 S Horizontal Output vertical output vertical upwards from a horizontal position

Clamping hub diameter (see technical data sheet for possible diameters)

Code letter	mm	Code letter	mm
В	11	I	32
С	14	К	38
Е	19	М	48
G	24	N	55
Н	28		

Intermediate sizes possible using bushings with a minimum thickness of 1 mm.

Hypoid and bevel gearboxes

For information purposes only – not required when placing orders!

Permitted standard mounting positions for right-angle gearboxes (see illustrations)

If the mounting position is different, contact WITTENSTEIN alpha without fail

B5 / V3
Output horizontal /
motor shaft vertical upwards





V3/B5 Output vertical upwards / motor shaft horizontal

B5 / V1
Output horizontal /
motor shaft vertical downwards





B5/B5 Output horizontal /

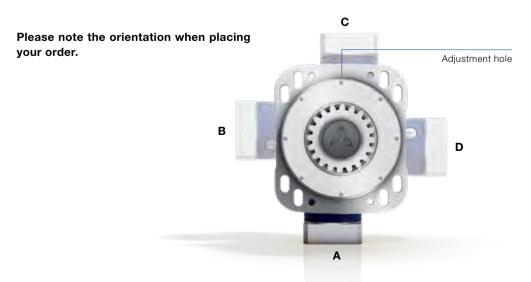
motor shaft horizontal

V1 / B5 Output vertical downwards / motor shaft horizontal





Orientation to the application





alpha

WITTENSTEIN alpha GmbH Walter-Wittenstein-Straße 1 97999 Igersheim Germany Tel. +49 7931 493-0

24h-Service-Hotline: Tel. +49 7931 493-12900

 $speedline^{\text{@}}\text{: Tel. } +49\ 7931\ 493\text{-}10444$

info@wittenstein-alpha.com

WITTENSTEIN alpha – Intelligent drive systems

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alpha Advanced Line. Maximum power density and outstanding positioning accuracy for complex applications.





alpha Basic / Value Line. Reliable, flexible and economical solutions for a wide range of applications.





alpha Linear Systems. Precise, dynamic system solutions for every requirement.





alpha Mechatronic Systems. Energy-efficient, versatile and flexible mechatronic drive systems.